



Constrained Horn Clauses for Verification and Synthesis

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Automated Reasoning about Software



Logic-based verification and synthesis

A user provides a program and a desired specification

E.g., program never writes outside of allocated memory

A tool automatically constructs a model of the program

Program = formula

Use decision procedures to reason about formulas

Thus, deriving properties about programs

Inspired by methods in applied science

E.g., physicists in 17-19th centuries



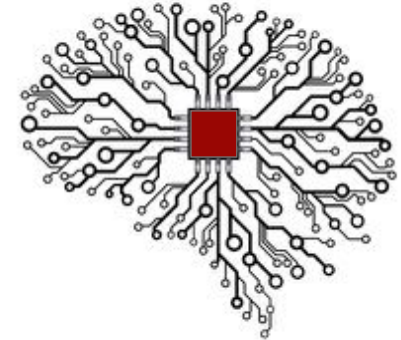
Automated Reasoning Today

Automated verification with SMT solvers

- Scale to large industrial applications

Constrained Horn Clauses (CHC):

- Symbolic representation of programs
- Safety specifications (assertions)



Verification = CHC translation + CHC solving

- E.g., *SeaHorn* + *Spacer*, *JayHorn* + *Eldarica*, or *RustHorn* + *Holce*

“Guess-and-check” invariant generation for CHC solving:

- Iteratively construct proofs using SMT solvers

Successful techniques are based on simple ideas

- Property Directed Reachability / IC3
- Machine Learning / Syntax-Guided methods

SAT: Boolean Satisfiability

Given a Boolean expression, using “and” (\wedge),
“or” (\vee) and “not” (\neg),

- Is there an assignment of *true* and *false* to the variables that makes the expression equal *true*?

Example:

- $(x \vee \neg y) \wedge (x \vee z \vee w) \wedge \neg z \wedge (w \vee y)$
- Solution: $x = y = w = \text{true}, z = \text{false}$

DPLL (Davis-Putnam-Logemann-Loveland, '60)

- Smart enumeration of all possible SAT assignments

Many heuristics used by modern tools

- Allow solving instances with millions of variables

SMT: Satisfiability Modulo Theory

Satisfiability of Boolean formulas over atoms in a theory

- E.g., $x > 2 * y - 1 \wedge y < 4$
- A solution: $x = y = 0$

Extends syntax of Boolean formulas with functions and predicates

- $+$, $-$, div , $select$, $store$, $bvadd$, etc.

Existing solvers support many theories useful for program verification

- Equality and Uninterpreted Functions: $x = y \implies f(x) = f(y)$
- Real/Integer Linear Arithmetic: $x > 2 * y - 1 \wedge y < 4$
- Unbounded Arrays: $A = store(B, i, select(C, j))$
- Bitvectors (a.k.a. machine integers): $y = x \gg 4 \wedge z = y \& x$
- Floating point: $0.1 * x = 3.6 * y$

Solving based on SAT

- As well as multiple heuristics for the theory reasoning

CHC: Constrained Horn Clauses

Formula in first order logic:

$$\varphi \wedge p_1(V) \wedge \dots \wedge p_k(V) \implies H$$

- where A is a constraint language
(e.g., (non-)linear arithmetic, arrays, bit-vectors, etc.)
- φ is a constraint in A
- $p_1 \dots p_k$ are uninterpreted relation symbols
- each $p_i(V)$ is an application of the predicate to variables
- H is either some application $p_i(V)$ or *false*

System of CHCs

- Only one CHC with $H = \textit{false}$
- **Has a solution** if there exists an interpretation for each p_i
making each CHC valid

CHC Solvers

IC3/PDR

[Hoder, Bjorner, SAT'12]

[Cimatti, Griggio, CAV' 12]

[McMillan, CAV'14]

[Komuravelli, Gurfinkel, Chaki,
Clarke, CAV'14]

CEGAR

[Unno, Terauchi, TACAS'15]

[Hojjat, Ruemmer, FMCAD'18]

[Vazou, Seidel, Jhala, etc, ICFP'14]

[Dietsch, Heizmann, Hoenicke, Nutz,
Podelski, HCVS/PERR'19]

Abstract Interpretation

[Kafle, Gallagher, Morales, CAV'16]

[Bakhirkin, Monniaux, SAS'17]

CEGIS/SyGuS

[Beyene, Popeea, Rybalchenko, CAV'13]

[Fedyukovich, Prabhu, Madhukar, Gupta,
FMCAD'18]

ML

[Champion, Chiba, Kobayashi, TACAS'18]

[Zhu, Magill, Jagannathan, PLDI'18]

Abduction

[Dillig, Dillig, Li, McMillan, OOPSLA'13]



The rest of the talk

[all papers co-authored by Fedjukovich]

FMCAD 2017:

Sampling Invariants from Frequency Distributions

CAV 2019:

Quantified Invariants via Syntax-Guided Synthesis

TACAS 2021:

Bridging Arrays and ADTs in Recursive Proofs

CP 2019:

Lemma Synthesis for Automating Induction over Algebraic Data Types

PLDI 2021:

Specification Synthesis with Constrained Horn Clauses

Example

Program in C

CHC-encoding

Symbolic execution (via *static single assignment* transformation)

Uninterpreted predicate

```
int j, m, N = nondetInt();
int *A = nondetArray(N);
int i = 0;
```

```
while (i < N) {
    if (m < A[i]) m = A[i];
    i++;
}
```

```
assume(0 ≤ j < N);
assert(m ≥ A[j]);
```

$$i = 0 \implies \textit{inv}(A, i, m, N)$$

$$\textit{inv}(A, i, m, N) \wedge i < N \wedge$$

$$m' = \textit{ite}(m < A[i], A[i], m) \wedge$$

$$i' = i + 1 \implies \textit{inv}(A, i', m', N)$$

$$\textit{inv}(A, i, m, N) \wedge i \geq N \wedge$$

$$0 \leq j < N \wedge \neg(m \geq A[j]) \implies \perp$$

Verification Conditions as CHCs

Compact representation of a loop

$$\begin{aligned}\text{INIT}(V) &\implies \text{Inv}(V) \\ \text{Inv}(V) \wedge \text{TR}(V, V') &\implies \text{Inv}(V') \\ \text{Inv}(V') \wedge \text{BAD}(V') &\implies \perp\end{aligned}$$

Getting finite traces

- Unroll the loop some k times
- Evaluate a so-called Bounded Model Checking (BMC) formula

$$\text{INIT}(V) \wedge \underbrace{\text{TR}(V, V') \wedge \text{TR}(V', V'') \wedge \dots \wedge \text{TR}(V^{(k-1)}, V^{(k)})}_k \wedge \text{BAD}(V^{(k)})$$

- here, each $V^{(i)}$ is a fresh copy of V

- Increase k for finding more bugs
- But to prove that there are no bugs, *we need inductive invariants*

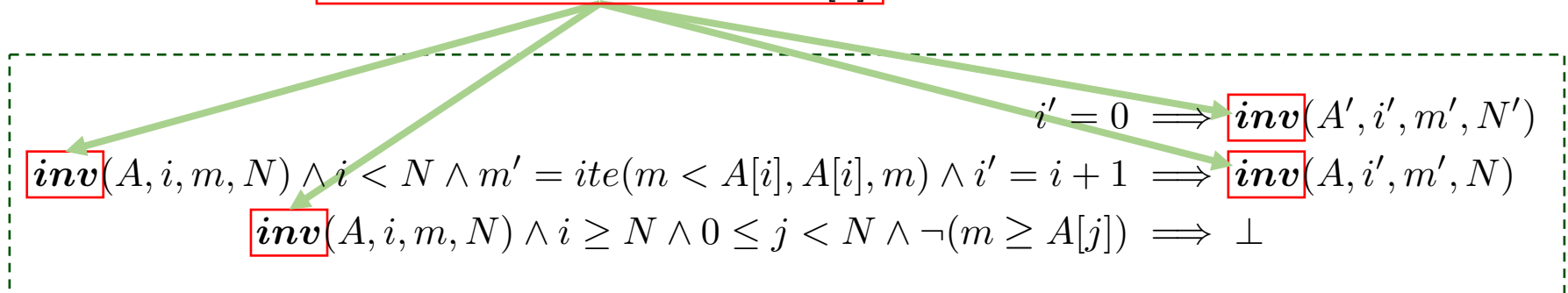
Solutions for CHCs

Inductive invariant:

- Describes all initial states
- If it describes a state from where a transition starts, then it describes a state where the transition ends
- Describes no bad states

Example

$$inv \mapsto \boxed{\forall j . 0 \leq j < i \implies m \geq A[j]}$$



Our approach: FREQHORN

[Fedyukovich et al, FMCAD'17]

High-level view:

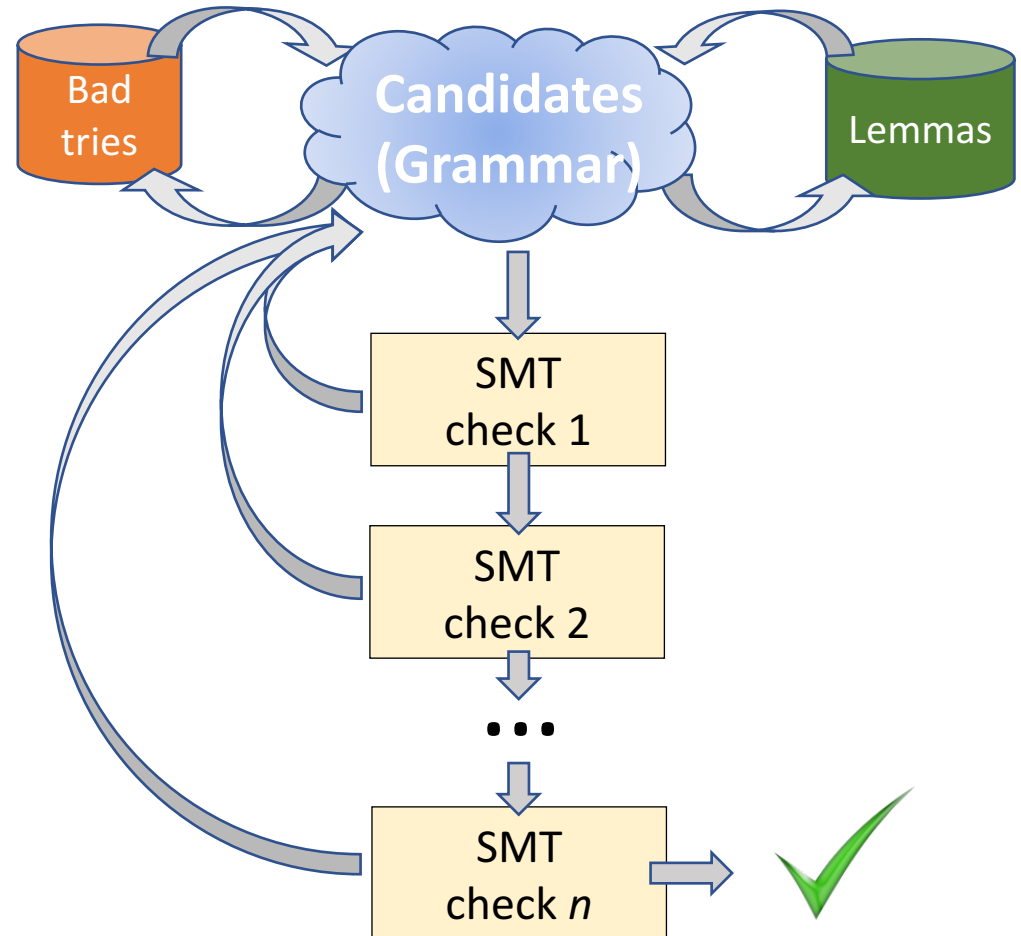
- Loop between a candidate generator and an SMT-solver

Candidate generator

- **Syntax-Guided Synthesis (SyGuS)**
- Learning from positive / negative candidates

SMT-based decision maker

- Off-the-shelf SMT solvers (for termination, non-termination, safety, etc...)



Quantified Solutions for CHCs

[Fedyukovich et al., CAV 2019]

Inductive invariant:

- Describes all initial states
- If it describes a state from where a transition starts, then it describes a state where the transition ends
- Describes no bad states

Example

quantified variable

progress range

cell property

$$inv \mapsto \forall j. [0 \leq j < i] \implies [m \geq A[j]]$$

$$\begin{aligned}
 & inv(A, i, m, N) \wedge i < N \wedge m' = \text{ite}(m < A[i], A[i], m) \wedge i' = i + 1 \implies inv(A, i', m', N) \\
 & i' = 0 \implies inv(A', i', m', N') \\
 & inv(A, i, m, N) \wedge i \geq N \wedge 0 \leq j < N \wedge \neg(m \geq A[j]) \implies \perp
 \end{aligned}$$

Obtaining Quantified Invariants

[Fedyukovich et al., CAV 2019]

$$\forall \vec{q} . \text{progressRange}(\vec{q}, \text{counters}) \implies \text{cellProperty}(\vec{q}, \text{vars})$$

Identify $\text{counters} \subseteq \text{vars}$

- Variables and the direction of their change

Introduce fresh variables \vec{q} to be quantified

- One per each counter
- Progress range based on termination conditions of loops and initial values of counters

SyGuS-based sampling of cell properties

- Using automatically generated formal grammars
- Similar to the case of numeric invariants

Relational Verification with CHCs

[Mordvinov et al., LPAR'2017, FMCAD'19]

Need for multiple invariants

- Solutions are often inexpressible in the constraint language

Program transformation should help

- Simplifies the verification condition
- Preserves semantics

Can be made directly on the level of CHCs

- Using a product-transformation

Applications:

- Information-flow Checking
- Equivalence Checking



Application: Bridging arrays and ADT

[Fedyukovich et al., TACAS'2021]

Data structures in programs

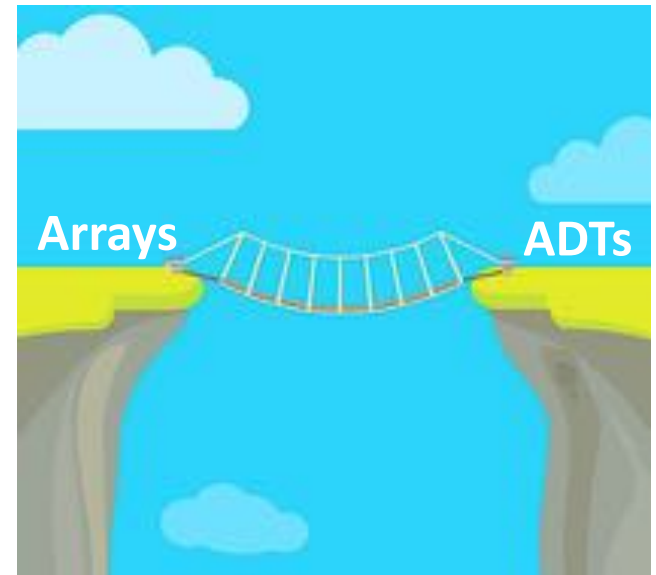
- Arrays
- Algebraic Data Types (ADT)

Automated reasoning is hard

- Arrays need (universal) *quantifiers*
- ADTs need *recursion*

Relational verification is even harder

- **Goal:** prove that an ADT-implementation and an Array-implementation of the same interface are equivalent
- **Solution:** synthesize relational invariants which are recursive and quantified



Example

Two implementations of a stack

```
class ListStack:
```

```
    def init():
```

```
        xs = nil
```

```
    def push(in):
```

```
        xs = cons(in, xs)
```

```
    def pop():
```

```
        assert xs != nil
```

```
        out = xs.head
```

```
        xs = xs.tail
```

```
        return out
```

```
class ArrStack:
```

```
    def init():
```

```
        n = 0
```

```
        a = [...]
```

```
    def push(in):
```

```
        a[n] = in
```

```
        n = n + 1
```

```
    def pop():
```

```
        assert n > 0
```

```
        n = n - 1
```

```
        return a[n]
```

Example

Two implementations of a stack

$$\mathbf{R}(xs, n, a) = \begin{cases} n = 0 & \text{if } xs = \text{nil} \\ n > 0 \wedge y = a[n - 1] \wedge \mathbf{R}(ys, n - 1, a) & \text{if } xs = \text{cons}(y, ys) \end{cases}$$

$$\mathbf{R}(xs, n, a) = \begin{cases} _ (n, a) & \text{if } xs = \text{nil} \\ _ (y, ys, n, a, _) \wedge \mathbf{R}(ys, _) & \text{if } xs = \text{cons}(y, ys) \end{cases}$$

generalize

$$\mathbf{R}(xs, cs) = \begin{cases} _ (cs) & \text{if } xs = \text{nil} \\ \exists cs_r . _ (y, ys, cs, cs_r) \wedge \mathbf{R}(ys, cs_r) & \text{if } xs = \text{cons}(y, ys) \end{cases}$$

return out

Key Ideas

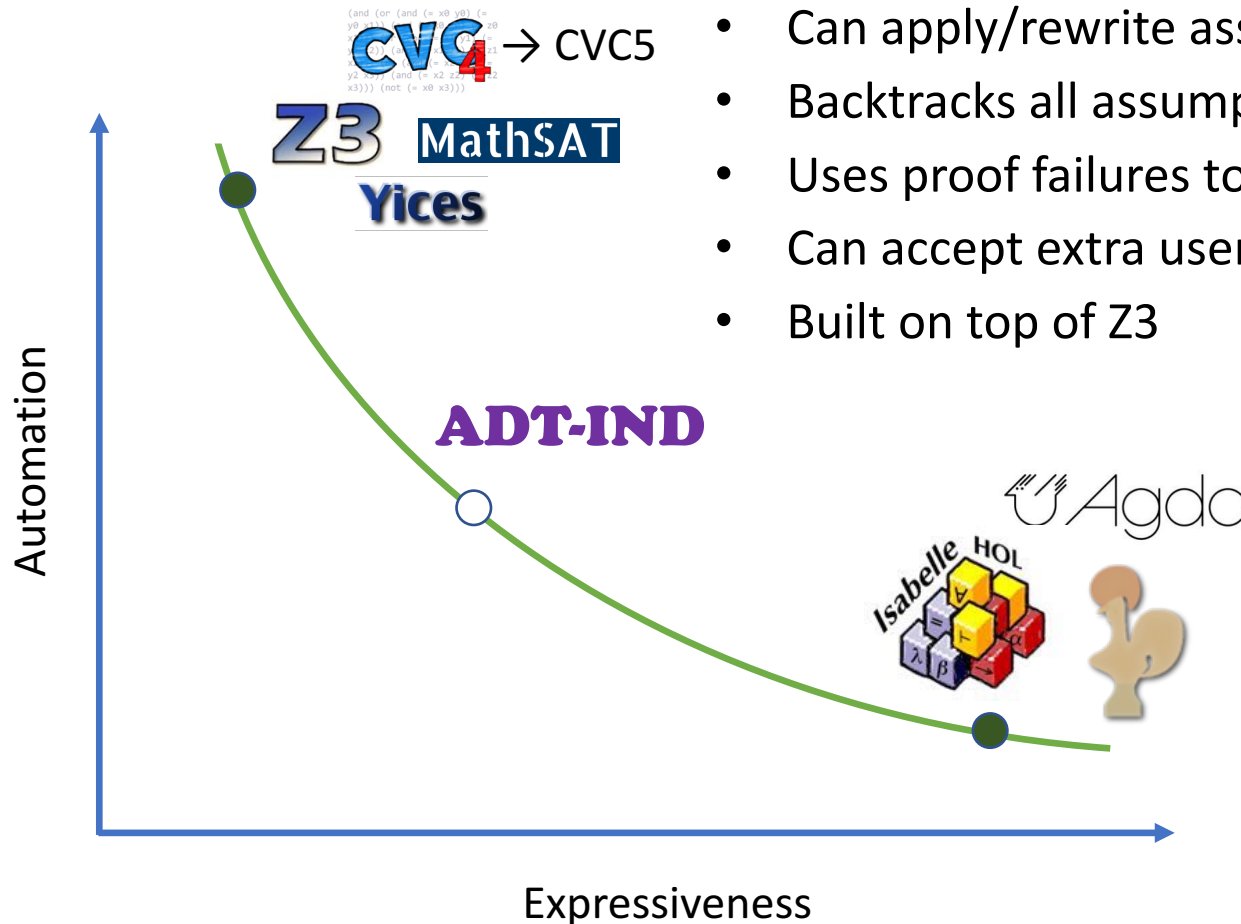
- Invariants describe the correspondence between programs in terms of the user-visible *input* and *output* variables
 - coincidence of preconditions
 - equivalence of outputs
 - the initiation and the consecution constraints
- Solutions for CHC use the recursive template
- CHC solver instantiates holes gradually
- CHC solver distinguishes:
 - *Producers*, i.e., that make the ADT “larger”
 - *Consumers*, i.e., that make the ADT “smaller”
 - *Noops*, i.e., that do not change the ADT

$$\mathbf{R}(xs, cs) = \begin{cases} _ (cs) & \text{if } xs = \text{nil} \\ \exists cs_r . _ (y, ys, cs, cs_r) \wedge \mathbf{R}(ys, cs_r) & \text{if } xs = \text{cons}(y, ys) \end{cases}$$

The **ADT-IND** prover

[Yang et al., CP'2019]

- Proves the validity of universally-quantified formulas by induction
- Can apply/rewrite assumptions
- Backtracks all assumptions fail
- Uses proof failures to synthesize lemmas
- Can accept extra user-lemmas
- Built on top of Z3



Specification Synthesis

```
int x = 19;  
while (*) {  
    int z = f();  
    x = x + z;  
}  
int y = g();  
assert(y >= x);
```

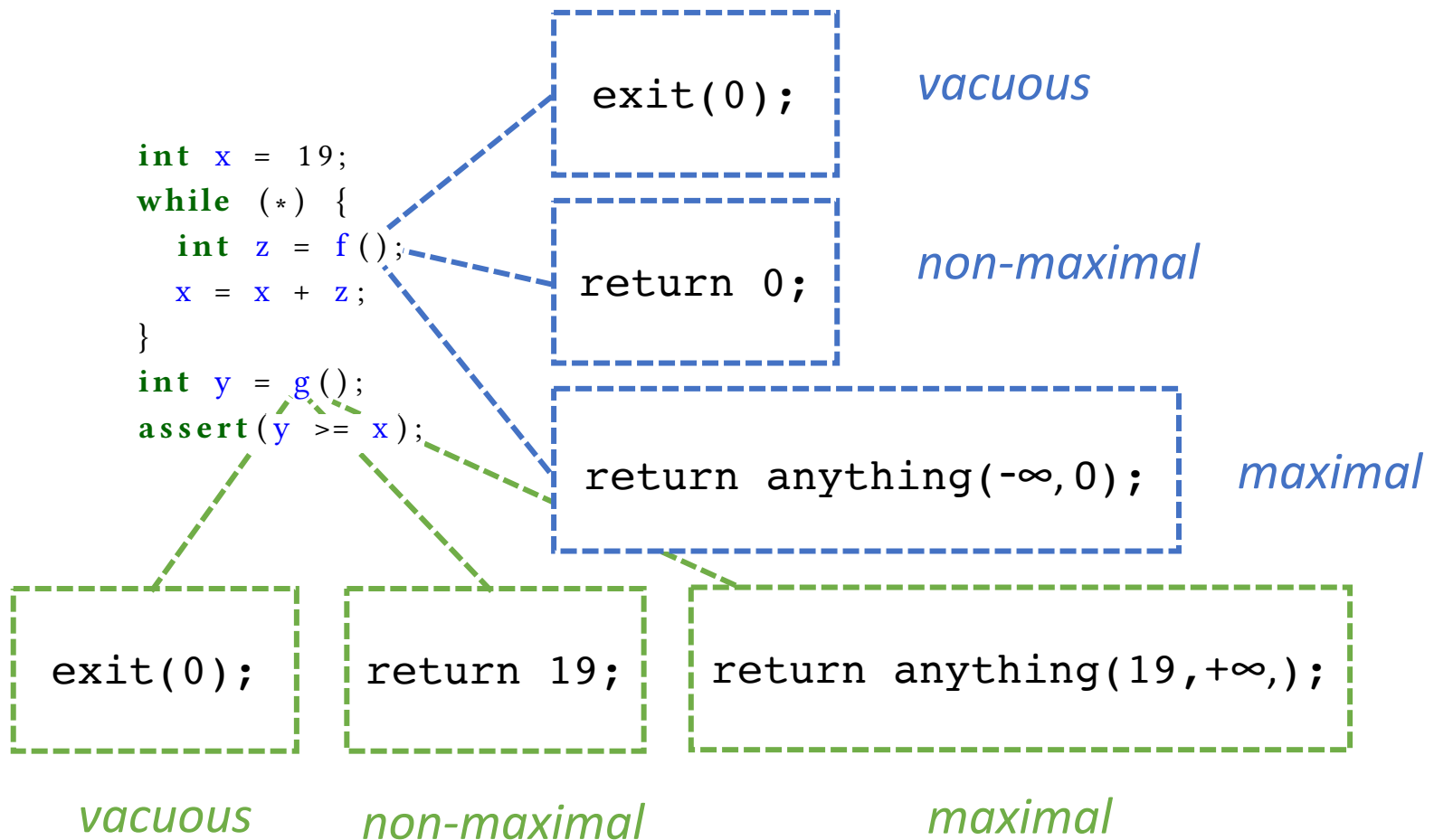
???

???

assertion should hold
for any
implementation

Specification Synthesis

Possible implementations



Specification Synthesis as CHC Problem

[Prabhu et al., PLDI'2021]

```
int x = 19;  
while (*) {  
    int z = f();  
    x = x + z;  
}  
int y = g();  
assert(y >= x);
```

$$x = 19 \implies \mathit{inv}(x)$$

$$\mathit{inv}(x) \wedge f(z) \wedge x' = x + z \implies \mathit{inv}(x')$$

$$\mathit{inv}(x) \wedge g(y) \wedge \neg(y \geq x) \implies \perp$$

Vacuous solutions

- Simply make the bodies of CHCs unsatisfiable
- Existing CHC solvers can easily discover them

Non-vacuous solutions

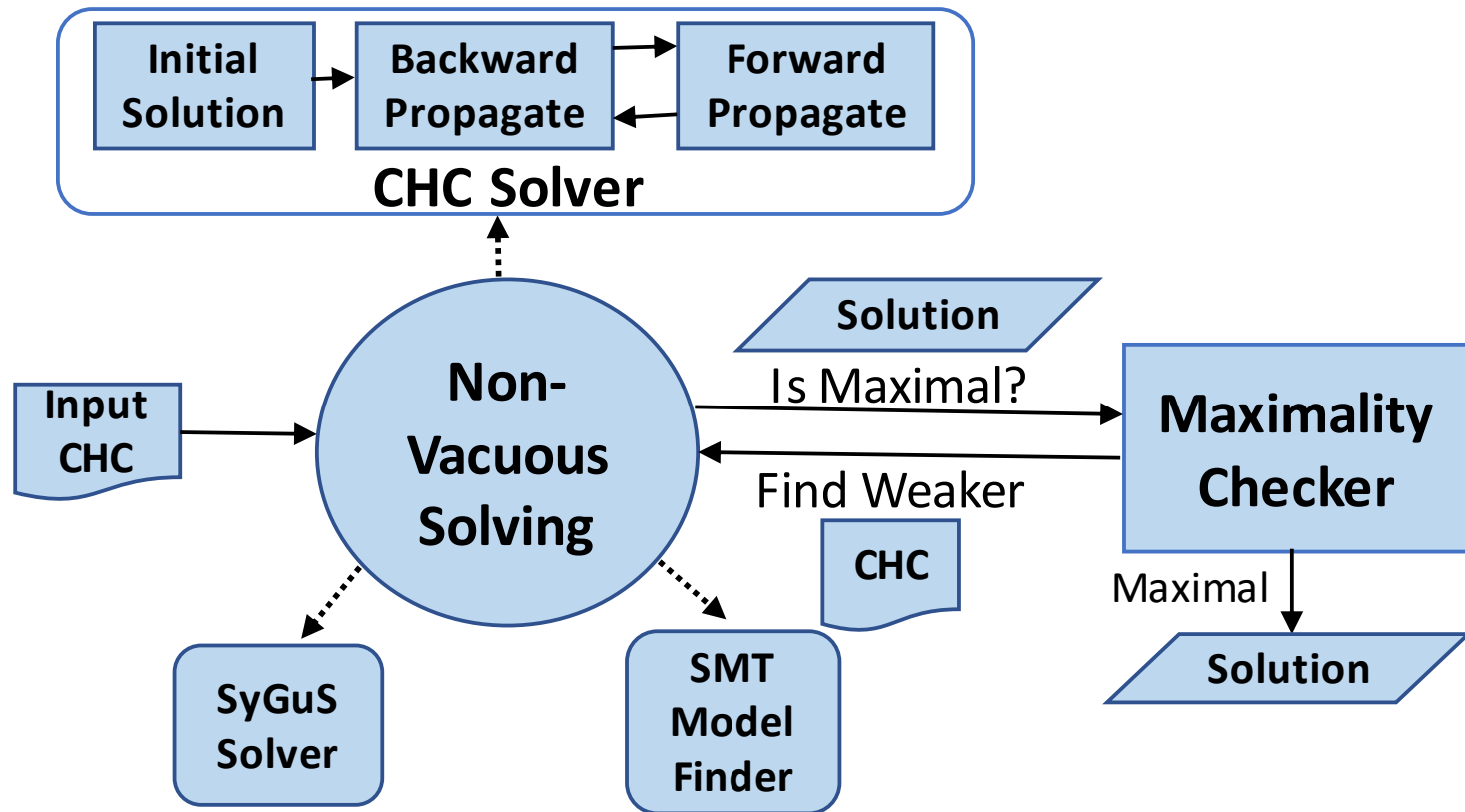
- Bodies of CHCs (and solutions) are satisfiable
- Require a CHC solver to do an extra SMT check for each solution

Maximal solutions

- Any weakening of solutions leads to assertion violation
- Require a CHC solver to check for assertion violations in a loop

HornSpec: Big idea

[Prabhu et al., PLDI'2021]



Evaluation

The tool

- FREQHORN <https://github.com/grigoryfeddyukovich/aeval/tree/rnd>
- Built on top of the Z3 SMT solver
- Fully automated workflow
- Parallelized using Message Passing Interface

Comparable with

- Spacer, Eldarica, HOICE, MCMC, ICE, etc
- > 500 public benchmarks

Strong points of FREQHORN

- Quantified Invariants over Arrays
- ADT support
- Forward/Backward propagation
using Quantifier Elimination
- Maximal Specification Synthesis



Conclusion and Future Work

- Safety verification
- Relational Verification
- Specification Synthesis

Solving Constrained Horn Clauses

- Automatic parallelization
- Security verification
- Termination Analysis

- Quantified Specification Synthesis
- Performance-aware Synthesis
- Termination-aware Synthesis