



# Learning-Based Controlled Concurrency Testing

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# Concurrent Programs

...are mainstream

...are extremely hard to get right

- uncontrolled non-determinism

...”Heisenbugs” (hard to detect, hard to replay)

...are difficult to test using traditional techniques

- exponentially large space of possible behaviors
- stress-tests are ineffective
- inability to deterministically replay bugs

# Controlled Concurrency Testing

Systematically explore space of program behaviors

...by *serializing* concurrent program executions

...using a *scheduler* which resolves control non-determinism

# Example

```
public class TestThreads {  
  
    public static volatile int Value;  
  
    public static void T1Proc () {  
        Thread.Sleep(100);  
        Value = 3;  
    }  
  
    public static void T2Proc () {  
        Thread.Sleep(100);  
        Value = 5;  
    }  
}
```

```
public static void main(String[] args) {  
  
    Thread t1 = new Thread(new ThreadStart(T1Proc));  
    Thread t2 = new Thread(new ThreadStart(T2Proc));  
  
    t1.Start();  
    t2.Start();  
    t1.Join();  
    t2.Join();  
  
    Assert(Value == 5);  
}
```

# Controlled Concurrency Testing

## Stateful

- Zing [*Andrews et al, 2004*]
- SPIN [*Holzmann, 1997*]
- DFS
- BFS

↓ Requires full-program state

## Stateless

- Random
- PCT [*Burckhardt et al, 2010*]
- Delay Bounding [*Emmi et al, 2011*]
- Preemption bounding [*Musuvathi et al, 2007*]

↑ PCT and Random known to be effective on real-world programs

↓ Search heuristics based on *empirical observations* of bug patterns

...few context switches

...few ordering constraints

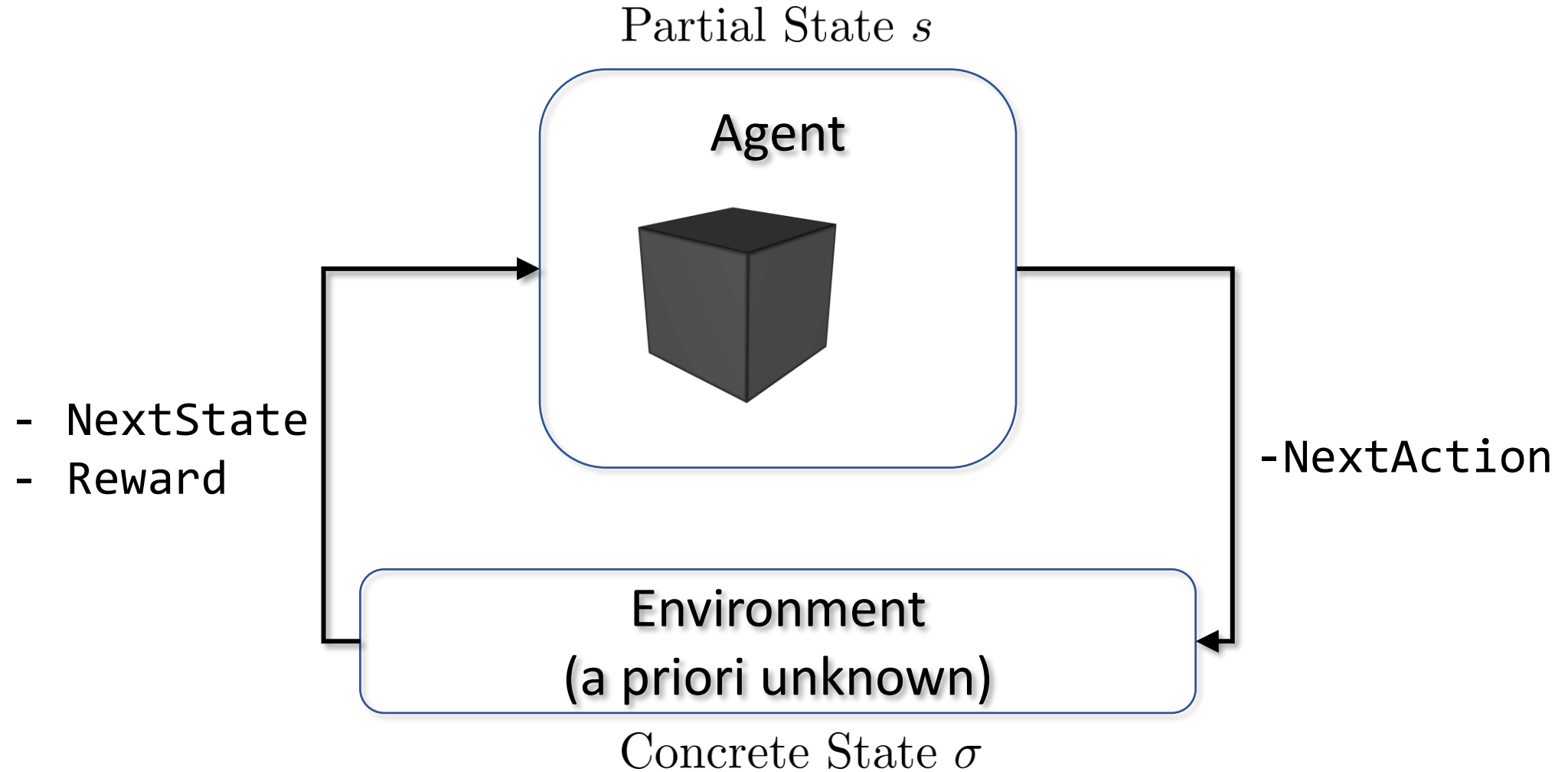
...few deviations from a deterministic scheduler

↓ What about unknown patterns?

# Our Contributions

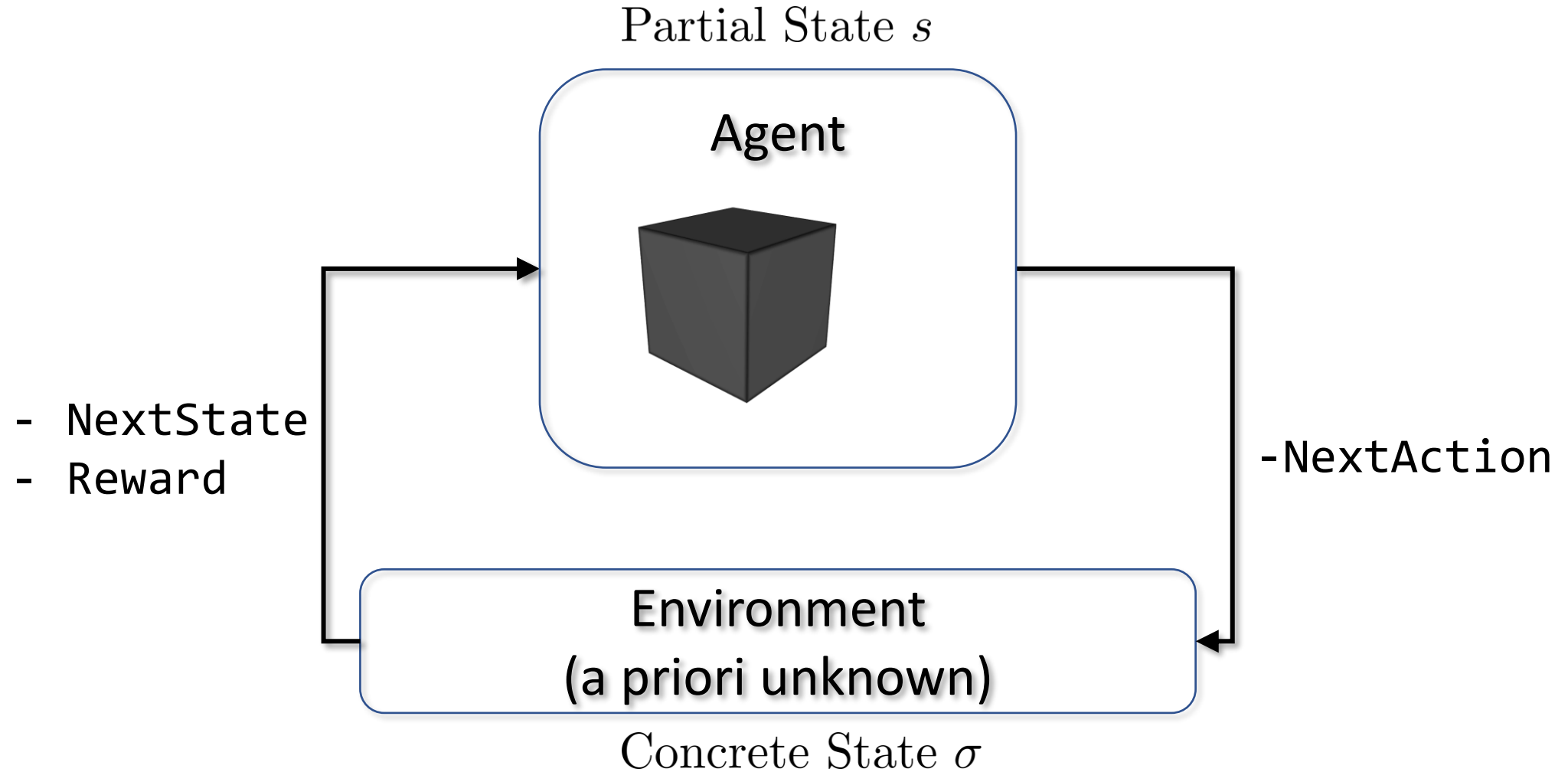
- Systematic exploration strategy based on *Q-Learning*
  - ...focus on *coverage*
  - ...strike a balance between *exploration* (randomly choose the next action)
  - ...and *exploitation* (learn from previously taken decisions)
- Highly customizable search strategy
  - ...that adapts to the program under test!
- Implemented in Coyote
  - Evaluated on micro-benchmarks and *production services* from Azure

# Reinforcement Learning



# Reinforcement Learning

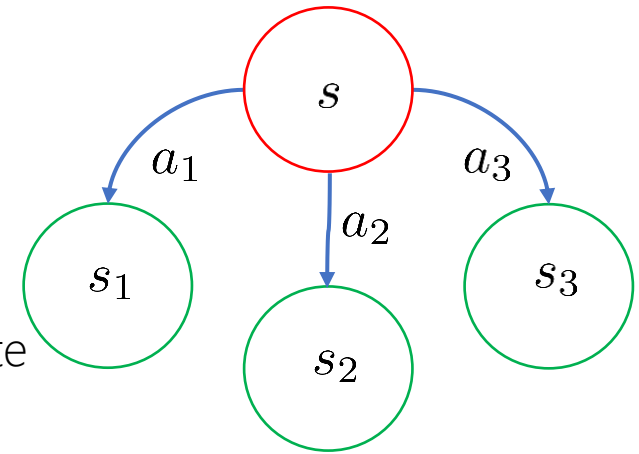
Goal of Agent: Learn an *optimal* policy, which *maximizes* expected reward





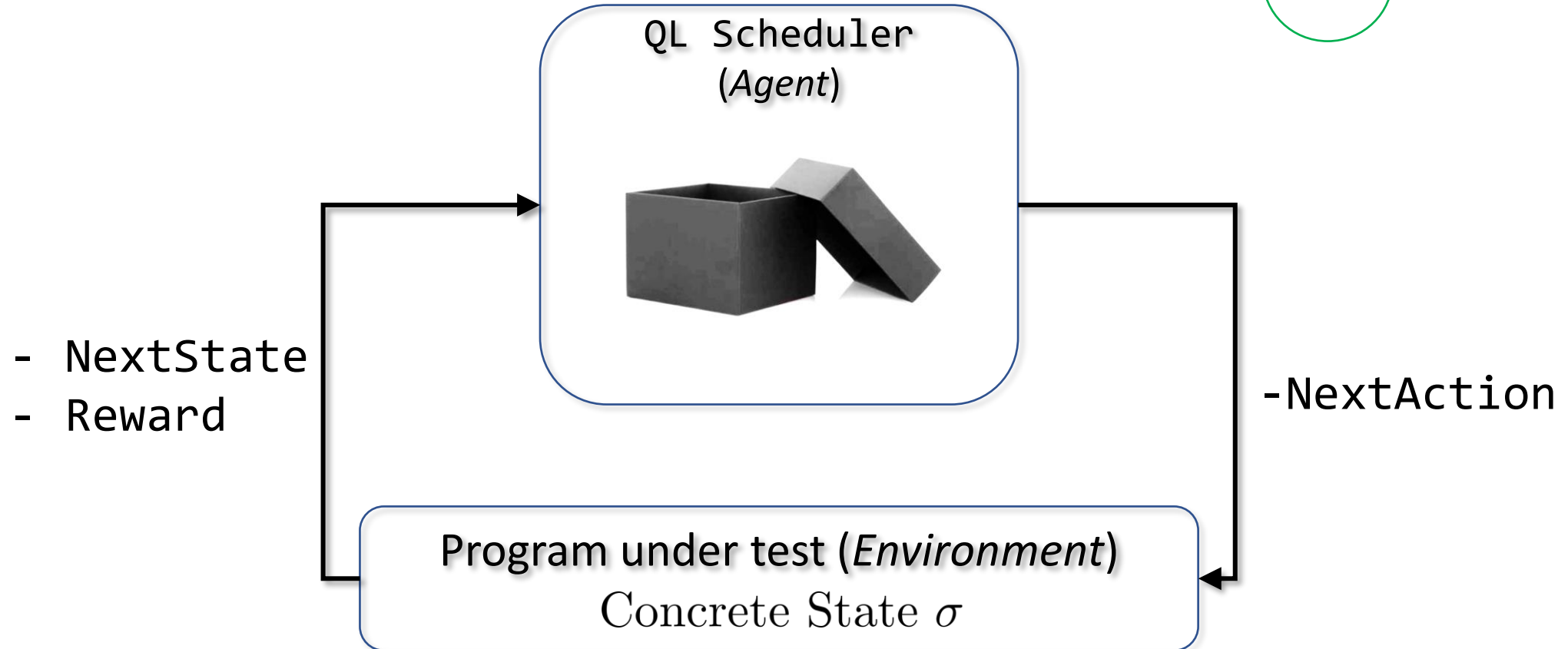
# Learning-based CCT

$Q(s, a_1)$   
 $Q(s, a_2)$   
 $Q(s, a_3)$



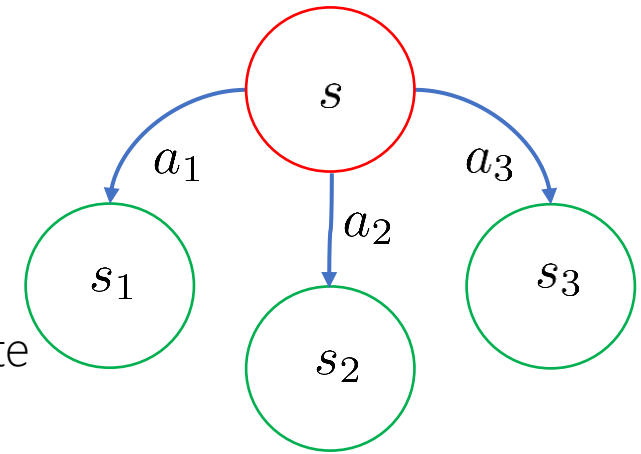
$$s = \mathcal{H}(\sigma)$$

User-defined abstraction of concrete state



# Learning-based CCT

$$Q(s, a_1)$$
$$Q(s, a_2)$$
$$Q(s, a_3)$$



$$s = \mathcal{H}(\sigma)$$

User-defined abstraction of concrete state

- NextState
- Reward

QL Scheduler  
(Agent)



-NextAction

$$P_s(a_i) \leftarrow \frac{e^{Q(s, a_i)}}{\sum_{j=1}^3 e^{Q(s, a_j)}}$$

Softmax

Program under test (Environment)

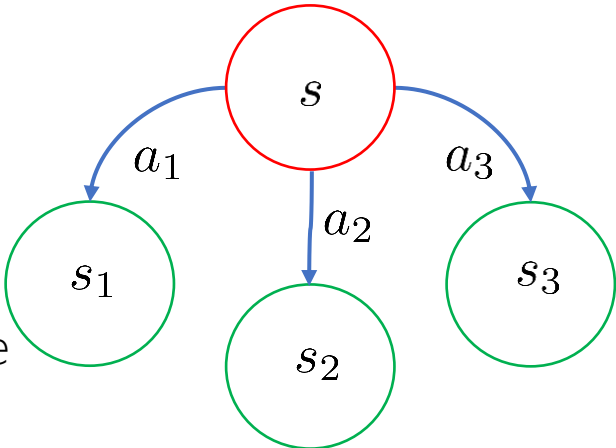
Concrete State  $\sigma$

# Learning-based CCT

$$Q(s, a_1)$$

$$Q(s, a_2)$$

$$Q(s, a_3)$$



$$s = \mathcal{H}(\sigma)$$

User-defined abstraction of concrete state

Value Update

$$Q(s, a_i) \leftarrow (1 - \alpha) \cdot Q(s, a_i) + \alpha \cdot (R(s, a_i) + \gamma \cdot \max Q_{s_i})$$



- NextState
- Reward
- (Penalty)



-NextAction

$$P_s(a_i) \leftarrow \frac{e^{Q(s, a_i)}}{\sum_{j=1}^3 e^{Q(s, a_j)}}$$

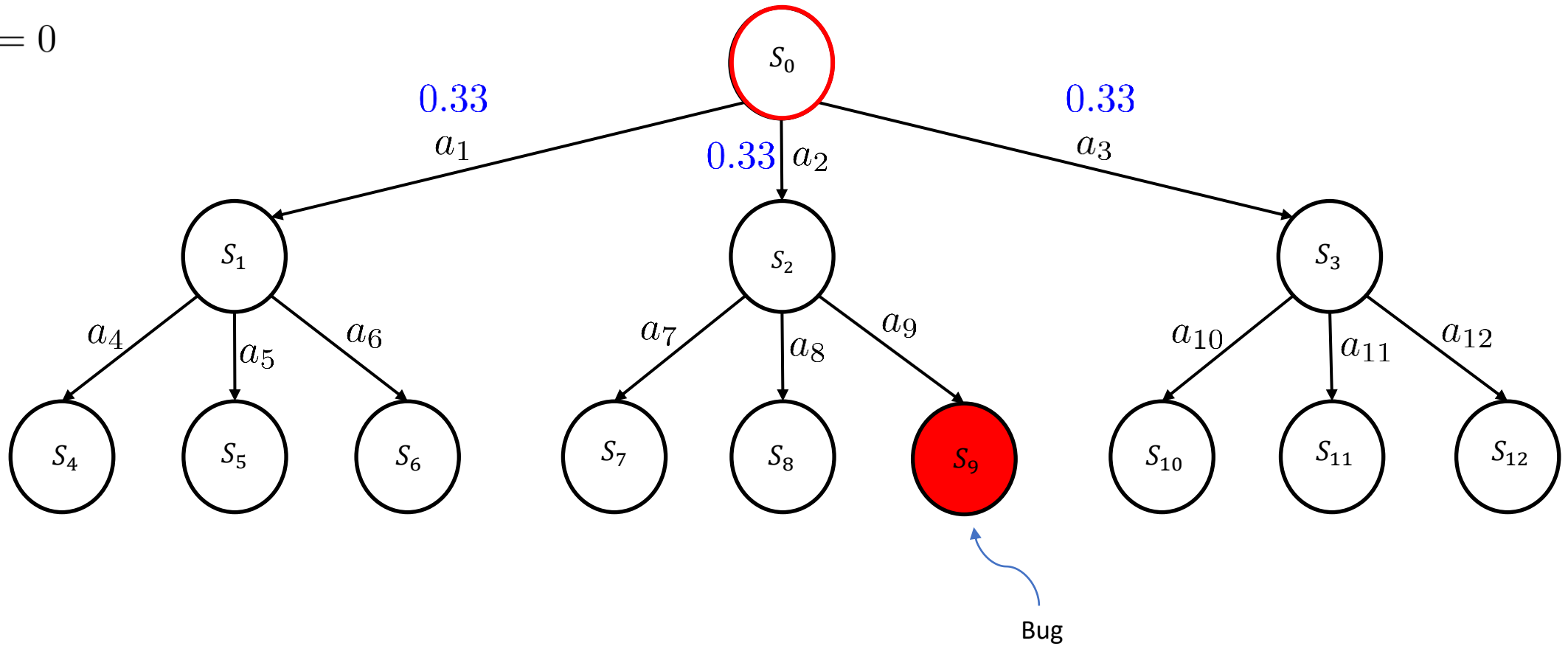
Softmax

# Controlled Concurrency Testing

$$Q(s_0, a_1) = 0$$

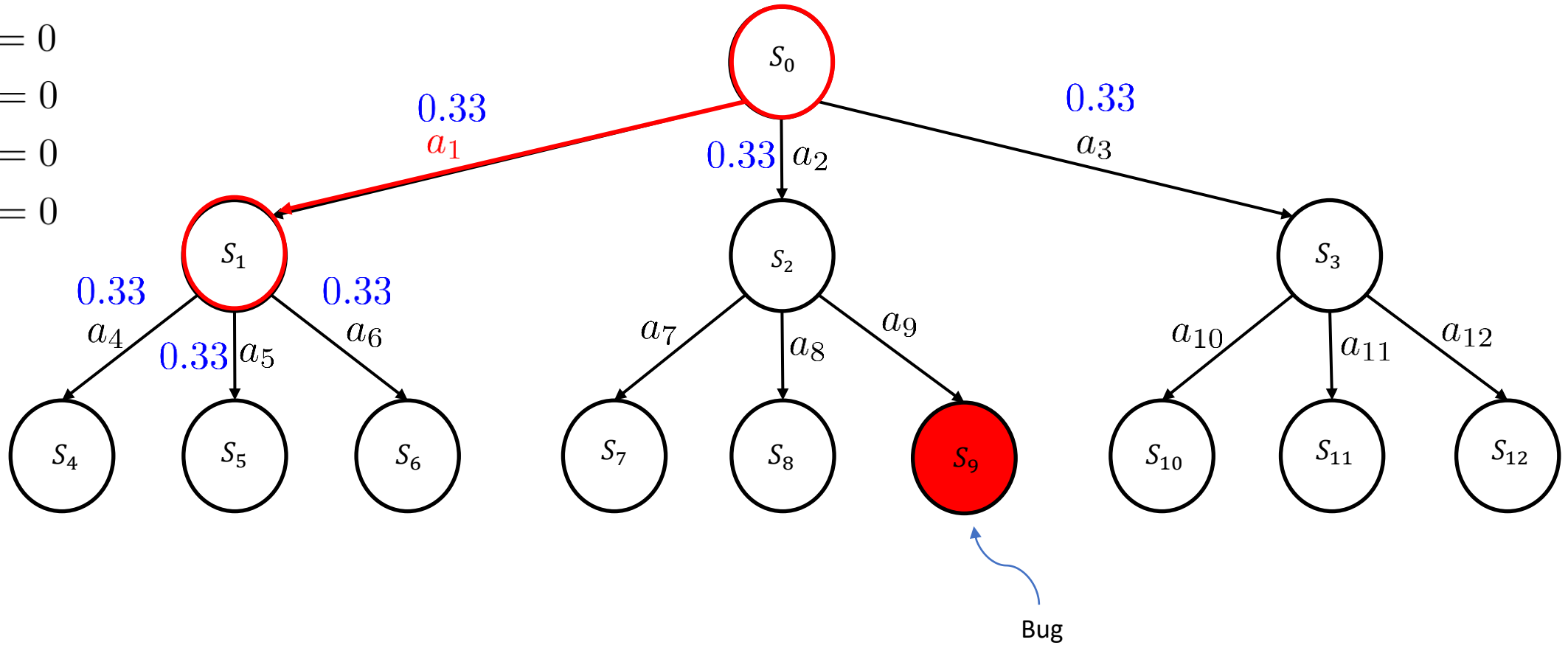
$$Q(s_0, a_2) = 0$$

$$Q(s_0, a_3) = 0$$



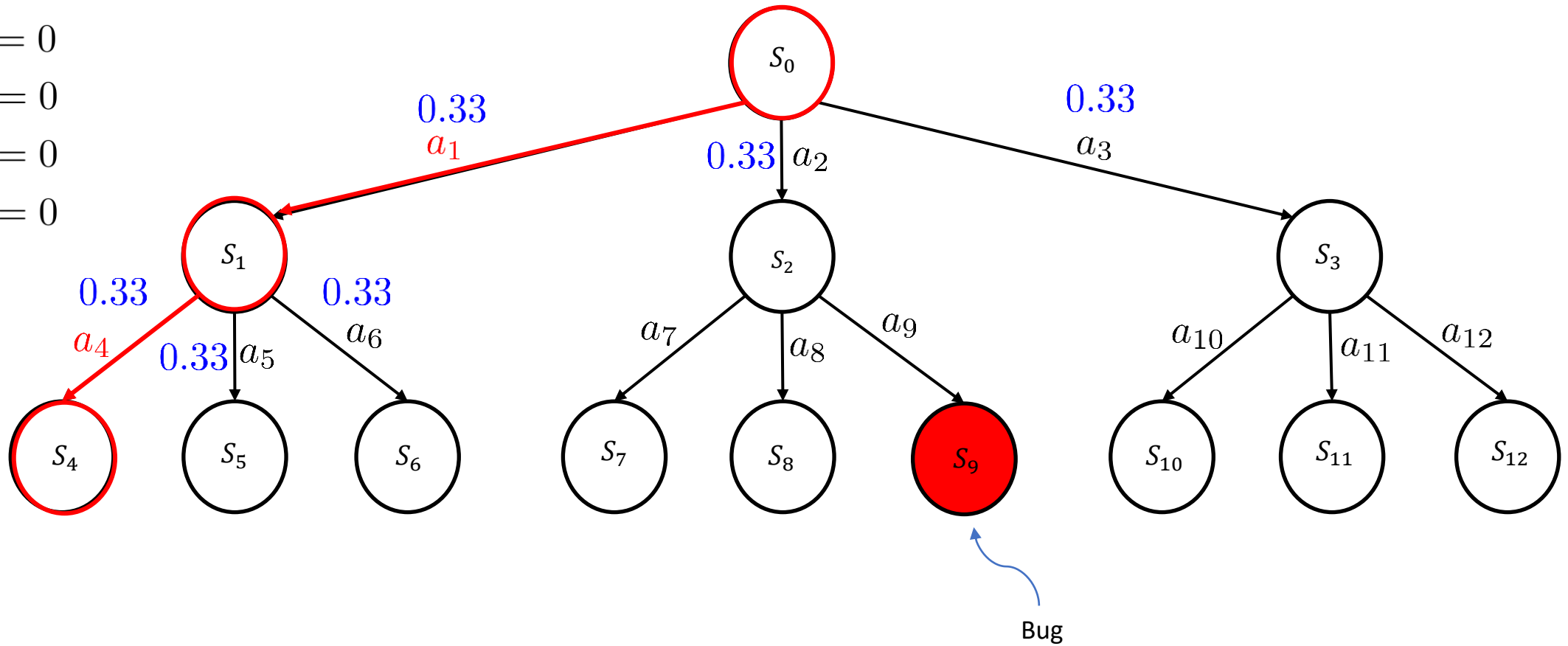
# Controlled Concurrency Testing

$$Q(s_0, a_1) = 0$$
$$Q(s_0, a_2) = 0$$
$$Q(s_0, a_3) = 0$$
$$Q(s_1, a_4) = 0$$
$$Q(s_1, a_5) = 0$$
$$Q(s_1, a_6) = 0$$



# Controlled Concurrency Testing

$$Q(s_0, a_1) = 0$$
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$$Q(s_1, a_4) = 0$$
$$Q(s_1, a_5) = 0$$
$$Q(s_1, a_6) = 0$$



# Controlled Concurrency Testing

$$Q(s_0, a_1) = -0.3$$

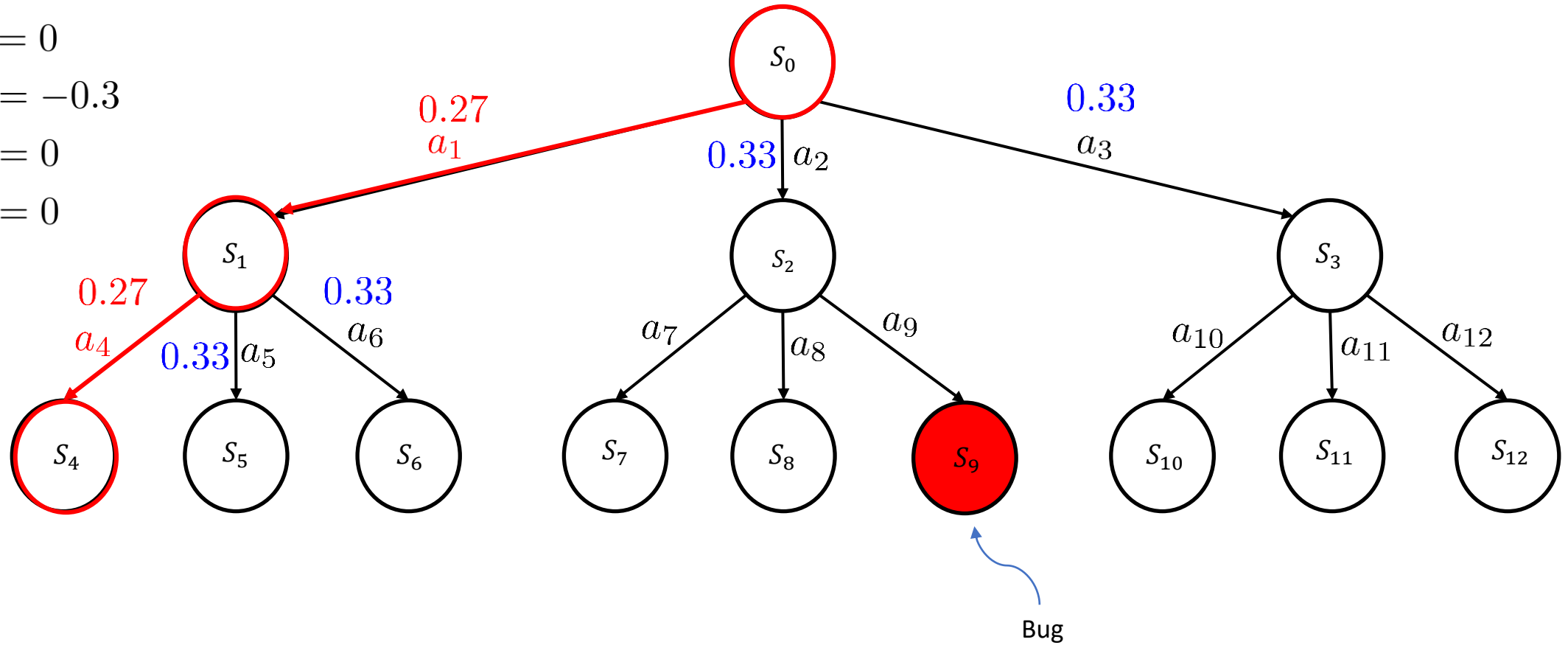
$$Q(s_0, a_2) = 0$$

$$Q(s_0, a_3) = 0$$

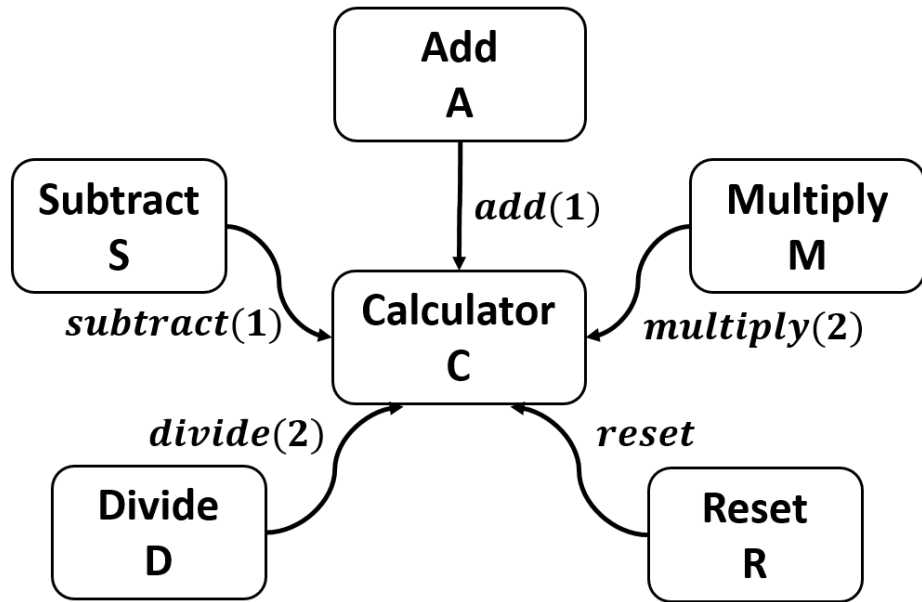
$$Q(s_1, a_4) = -0.3$$

$$Q(s_1, a_5) = 0$$

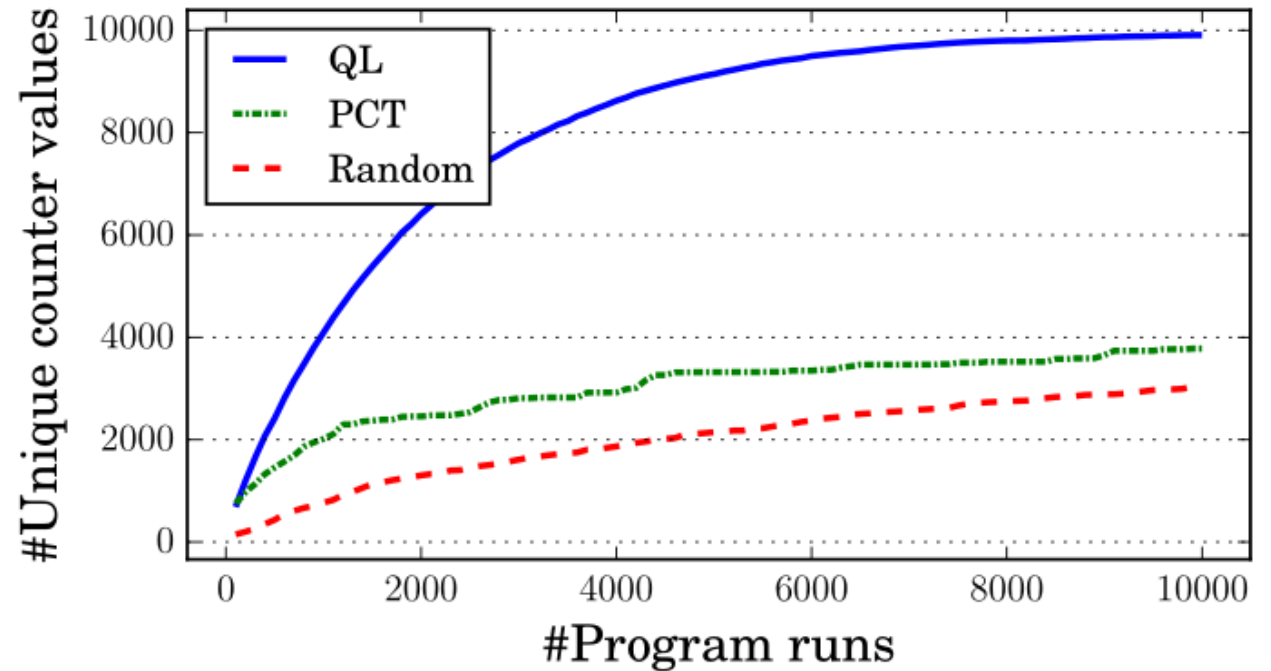
$$Q(s_1, a_6) = 0$$



# Optimizing for Coverage

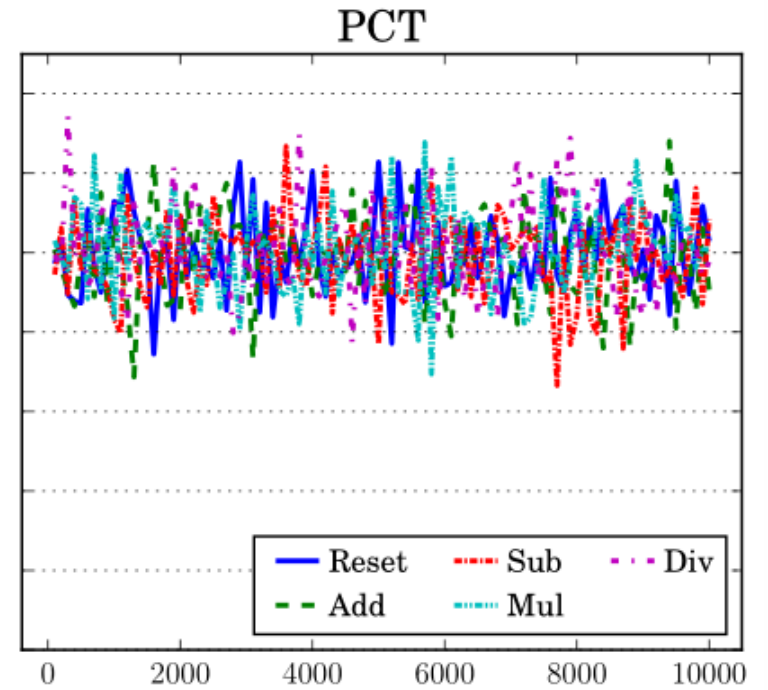
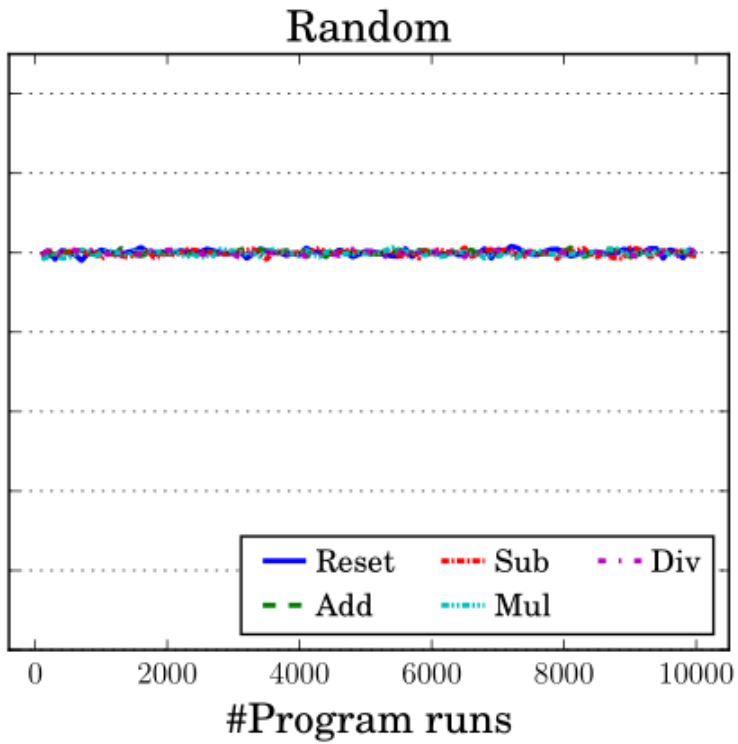
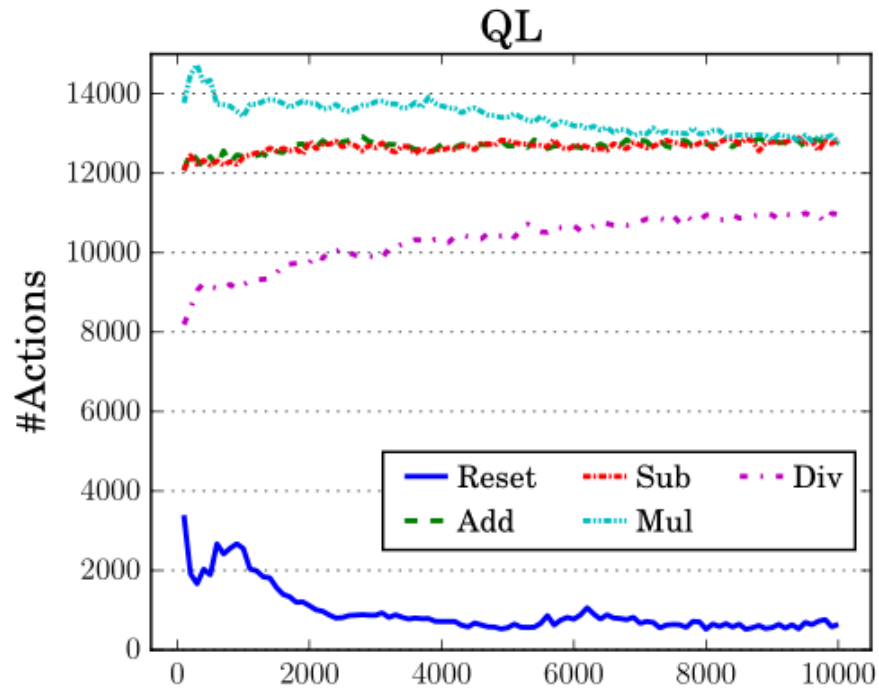


$-5000 \leq C.\text{counter} \leq 5000$





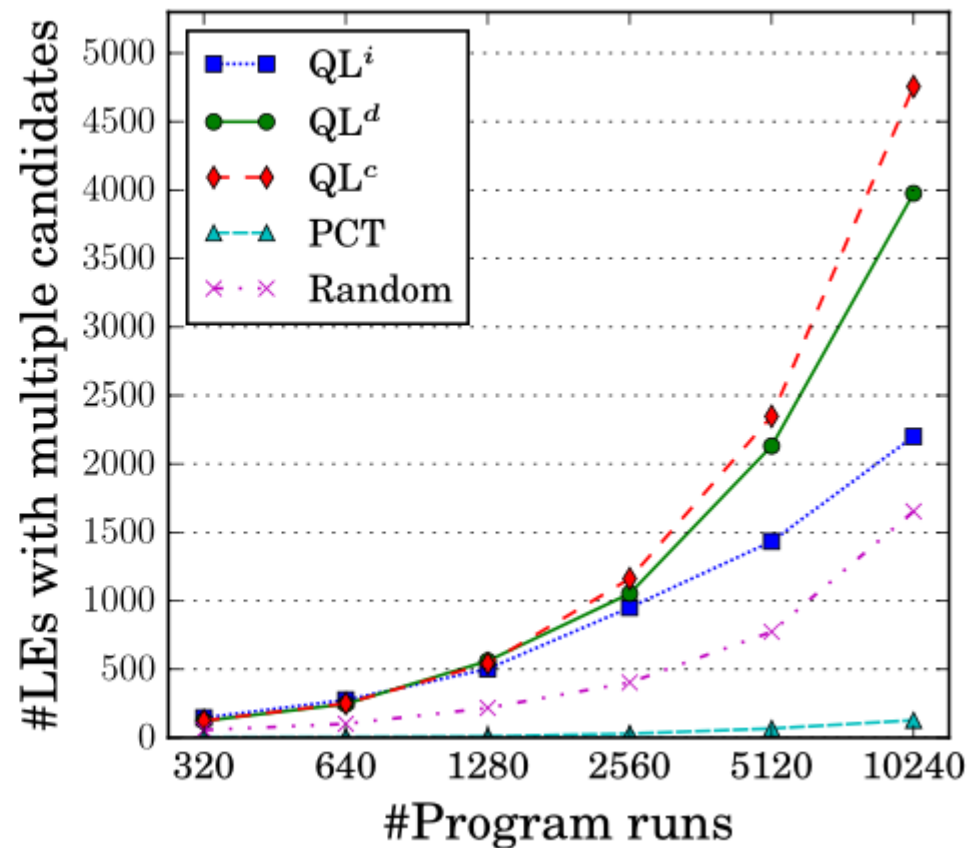
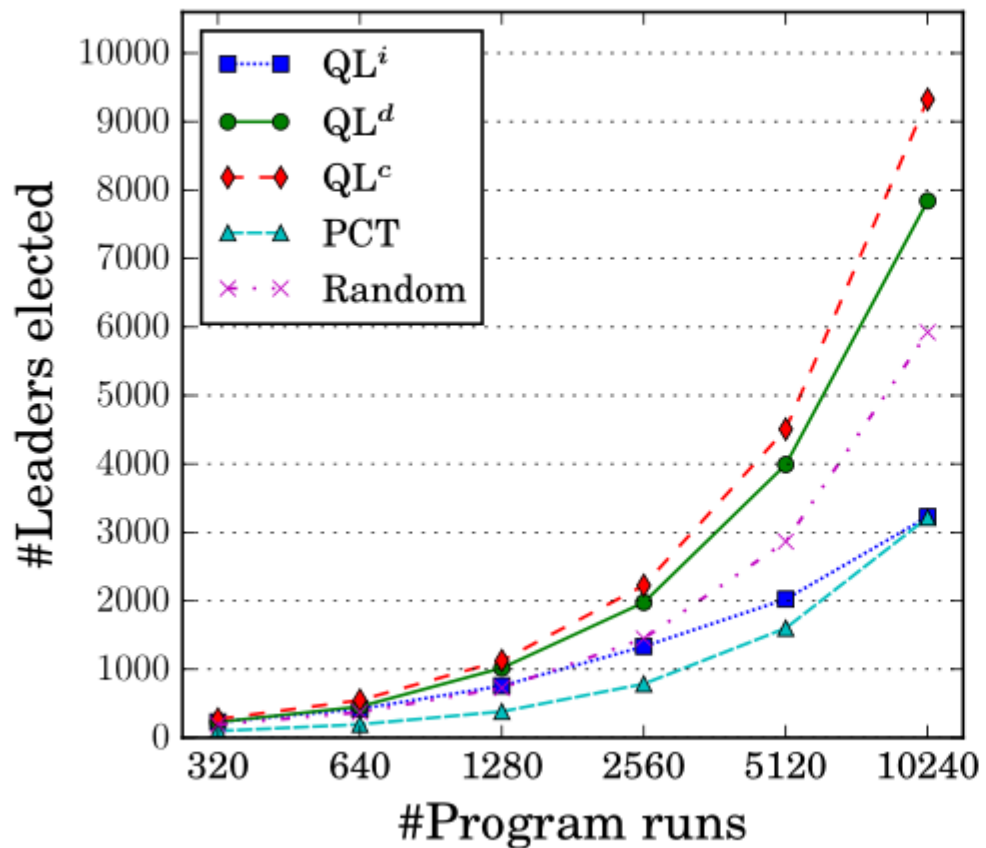
# Optimizing for Coverage



# Raft Consensus Protocol

- Nodes:
  - *Leader*: receive and replicate client requests
  - *Follower*: Track all requests received from leader
  - *Candidate*: start leader election process at any time
- Invariant:
  - *At most one leader at any point in time.*
- Buggy implementation: violates the invariant
- To increase likelihood of bug, increase:
  - At least one leader must be elected
  - Leader election round should have *multiple* candidates

# Raft Consensus Protocol



# Controlled Concurrency Testing

```
graph TD; A[Controlled Concurrency Testing] --> B[Stateful]; A --> C[H-Search QL]; A --> D[Stateless];
```

## Stateful

- Zing [Andrews et al, 2004]
- SPIN [Holzmann, 1997]
- DFS
- BFS

$\mathcal{H}$ -Search  
**QL**

## Stateless

- Random
- PCT [Burckhardt et al, 2010]
- Delay Bounding [Emmi et al, 2011]
- Preemption Bounding [Musuvathi et al, 2007]

# Experimental Evaluation

## *Effectiveness at bug-finding*

		Bugs <sup>100</sup>								
Benchmarks		LoC	#T	QL <sup>d</sup>	Random	Greedy	PCT-3	PCT-10	PCT-30	IDB
Protocols	Raft-v1	1194	17	99	<b>100</b>	83	<b>X</b>	12	45	28
	Raft-v2	1194	17	<b>95</b>	4	3	<b>X</b>	<b>X</b>	<b>X</b>	1
	Paxos	849	10	66	8	20	19	91	<b>92</b>	33
	Chord	859	7	<b>34</b>	<b>X</b>	<b>X</b>	<b>X</b>	<b>X</b>	<b>X</b>	<b>X</b>
	FailureDetector	692	5	99	<b>X</b>	<b>X</b>	11	<b>100</b>	99	31
Multithreaded	Fib-Bench-2	55	3	<b>100</b>	<b>100</b>	<b>100</b>	<b>X</b>	82	<b>100</b>	<b>100</b>
	Fib-Bench-Longest-2	55	3	<b>100</b>	<b>100</b>	<b>100</b>	<b>X</b>	<b>X</b>	<b>X</b>	<b>100</b>
	Triangular-2	73	3	<b>100</b>	86	<b>100</b>	<b>X</b>	<b>X</b>	2	70
	Triangular-Longest-2	73	3	<b>100</b>	<b>X</b>	79	<b>X</b>	<b>X</b>	<b>X</b>	<b>X</b>
	SafeStack	253	6	1	43	23	<b>X</b>	<b>X</b>	21	<b>46</b>
	BoundedBuffer	284	9	<b>53</b>	12	36	<b>X</b>	<b>X</b>	<b>X</b>	<b>X</b>
Production	PRODSERVICE1	56649	27	<b>79</b>	14	24	37	29	25	23
	PRODSERVICE2-v1	33827	15	<b>100</b>	<b>X</b>	<b>X</b>	<b>100</b>	<b>100</b>	37	<b>X</b>
	PRODSERVICE2-v2	33827	28	97	<b>X</b>	<b>X</b>	<b>100</b>	36	<b>X</b>	<b>X</b>
	PRODSERVICE3-v1	18663	17	92	<b>100</b>	16	76	96	80	<b>X</b>
	PRODSERVICE3-v2	19771	17	<b>100</b>	<b>100</b>	10	64	<b>100</b>	90	<b>X</b>
G-Mean Bugs <sup>100</sup>				<b>63.9</b> <sub>(16)</sub>	37.4 <sub>(11)</sub>	32.2 <sub>(12)</sub>	45.0 <sub>(7)</sub>	59.2 <sub>(9)</sub>	40.4 <sub>(10)</sub>	30.3 <sub>(9)</sub>

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# Summary

- Novel controlled concurrency testing, based on Q-Learning
  - balance between taking random steps and informed decisions based on previous explorations
- Evaluation: outperforms state-of-the-art strategies on **production Azure services**



# Big Picture

- Project Coyote: <https://github.com/microsoft/coyote>
  - Making testing of concurrent programs as easy as testing sequential programs
  - Used by many teams in Azure for writing distributed services
  - Includes great learning material for teaching concurrency-related concepts
- Extending beyond .NET [ASE'21]
  - Cross-platform solution for controlled-concurrency testing:  
<https://github.com/microsoft/coyote-scheduler>