

Safety Proofs using Appearance and Behaviours

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Inductive Invariants

```
int x = y = 0
while (*) {
    x = x + 1
    y = y + x
}
assert(y >= 0)
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```

Safe Inductive Invariants:

$$(x \geq 0 \wedge y \geq 0)$$

$$(x \geq 0 \wedge y - x \geq 0)$$

Inductive Invariants

Given $\langle V \cup V', \textit{Init}, \textit{Tr} \rangle$ and \textit{Bad}

Initiation: $\textit{Init}(V) \Rightarrow \textit{Inv}(V)$

Consecution: $\textit{Inv}(V) \wedge \textit{Tr}(V, V') \Rightarrow \textit{Inv}(V')$

Safety: $\textit{Inv}(V) \wedge \textit{Bad}(V) \Rightarrow \textit{false}$

Inductive Invariants

Given $\langle V \cup V', \text{Init}, \text{Tr} \rangle$ and Bad
 $\{x, y, x', y'\}, x = 0 \wedge y = 0, x' = x + 1 \wedge y' = y + x$ and $\neg(y \geq 0)$

Initiation: $\text{Init}(V) \Rightarrow \text{Inv}(V)$
 $(x = 0 \wedge y = 0) \Rightarrow (x \geq 0 \wedge y \geq 0)$

Consecution: $\text{Inv}(V) \wedge \text{Tr}(V, V') \Rightarrow \text{Inv}(V')$
 $(x \geq 0 \wedge y \geq 0) \wedge x' = x + 1 \wedge y' = y + x \Rightarrow (x' \geq 0 \wedge y' \geq 0)$

Safety: $\text{Inv}(V) \wedge \text{Bad}(V) \Rightarrow \text{false}$
 $(x \geq 0 \wedge y \geq 0) \wedge \neg(y \geq 0) \Rightarrow \text{false}$

Inductive Invariants

Given $\langle V \cup V', \text{Init}, \text{Tr} \rangle$ and Bad
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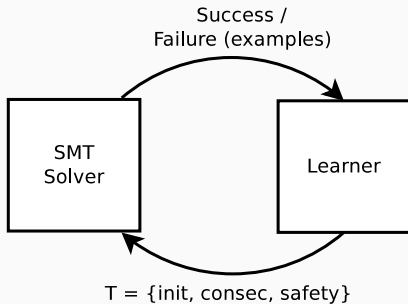
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Safety: $\text{Inv}(V) \wedge \text{Bad}(V) \Rightarrow \text{false}$
 $(x \geq 0 \wedge y \geq 0) \wedge \neg(y \geq 0) \Rightarrow \text{false}$

How to synthesize Inv ?

Guess and Check



Iterative learning: $Inv \Leftrightarrow I_0 \wedge I_1 \wedge \dots \wedge I_n$

Appearance Guided Synthesis

```
int x = y = 0
while (*)
  x = x + 1
  y = y + x

assert(y >= 0)
```

Probability distribution:

$$(x \geq 0) \mapsto 0.4$$

$$(-x \geq 0) \mapsto 0.0$$

$$(y \geq 0) \mapsto 0.3$$

$$(-y \geq 0) \mapsto 0.0$$

$$(x + y \geq 0) \mapsto 0.2$$

$$(y - x \geq 0) \mapsto 0.1$$

Appearance Guided Synthesis

```
int x = y = 0
while (*)
  x = x + 1
  y = y + x

assert(y >= 0)
```

Fedyukovich, Kaufman, and
Bodík, FMCAD 2017

Sampling Grammar

$c ::= 0 \mid 1 \mid -1$

$k ::= 0 \mid 1 \mid -1$

$v ::= x \mid y$

$lincom ::= k \cdot v + \dots k \cdot v$

$ineq ::= lincom \geq c \mid$

$lincom > c$

$cand ::= ineq \vee ineq \vee \dots ineq$

Appearance Guided Synthesis

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int x = y = 0
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  x = x + 1
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assert(y >= 0)
```

How often does a disjunctive formula have the arity i

How often does an operator $op \in \{>, \geq\}$ appear among the inequalities

How often does a variable v have a coefficient k

Appearance Guided Synthesis

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int x = y = 0
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  x = x + 1
  y = y + x

assert(y >= 0)
```

How often does a disjunctive formula have the arity i

$$p_{\vee}(2) = 0$$

How often does an operator $op \in \{>, \geq\}$ appear among the inequalities

$$p_{>} = 1/5$$

How often does a variable v have a coefficient k

$$p_{\{1,x\}}(1) = 1/2$$

Detective Auguste Dupin gave them a 'stong acceptance' as they found what was hidden in plain sight.

Relearning Probabilities

Avoid candidates that are:

Already checked

Stronger than failures

$$(x > 5 \vee x + y \geq 0) \supset (x > 10 \vee x + y > 5)$$

Weaker than learned lemmas

$$(y \geq 0 \vee y - x \geq 10) \subset (y \geq -1 \vee y - x > 8)$$

Increase probability of candidates that are unrelated

Experimental Evaluation

On 76 loopy programs, this technique outperformed

- ▷ μZ on 37 benchmarks (including 32 for which μZ crashed or timed out after 10 minutes)
- ▷ ICE-DT on 53 benchmarks (including 30 ...)
- ▷ MCMC on 67 benchmarks (including 49 ...)

Downsides

Equal treatment of all syntactic expressions

Ignorance to whether the candidates have a semantic value

Inability to predict an appropriate order of candidates to be sampled and checked

Downsides

```
int x = k = c = 0;
int N = *;
while (c < N)
    int M = *;
    if (k mod 2 == 0)
        x = x + M;
    c = c + M;
    k = x + c;

assert(x >= N);
```

Inductive Invariant1:

$$k \bmod 2 = 0 \wedge x = c$$

Inductive Invariant2:

$$k = x + c \wedge x = c$$

Accelerating Synthesis

Fedyukovich, and Bodík, TACAS 2017

Usage of Interpolation

Safety Proofs from Bounded Model Checking

Batch-wise candidate check

for each $cand \in candidates$
 $\bigwedge_{c \in candidates} c(V) \wedge Tr(V, V') \Rightarrow cand(V')$

Accelerating Synthesis

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int N = *;
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  int M = *;
  if (k mod 2 == 0)
    x = x + M;
  c = c + M;
  k = x + c;

assert(x >= N);
```

BMC:

$x = 0 \wedge k = 0 \wedge c = 0 \wedge \neg(c < N) \wedge \neg(x \geq N)$

Accelerating Synthesis

```
int x = k = c = 0;
int N = *;
while (c < N)
  int M = *;
  if (k mod 2 == 0)
    x = x + M;
  c = c + M;
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assert(x >= N);
```

BMC:

$x = 0 \wedge k = 0 \wedge c = 0 \wedge \neg(c < N) \wedge \neg(x \geq N)$

Interpolants:

$\{x \geq 0, c \leq 0\}, \{x = c\}, \{x \geq c\}$

Accelerating Synthesis

```
int x = k = c = 0;
int N = *;
while (c < N)
  int M = *;
  if (k mod 2 == 0)
    x = x + M;
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assert(x >= N);
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BMC:

$x = 0 \wedge k = 0 \wedge c = 0 \wedge \neg(c < N) \wedge \neg(x \geq N)$

Interpolants:

$\{x \geq 0, c \leq 0\}, \{x = c\}, \{x \geq c\}$

Candidates:

$k = x + c \wedge k \text{ mod } 2 = 0$

Behaviour as Data

Prabhu, Madhukar, Venkatesh, SAS 2018, *to appear*

```
assume(1 <= n <= 1000);
sum = 0, i = 1;
while(i<=n) {
  sum = sum + i;
  i = i + 1;
}
assert(2*sum == n*(n+1));
```

Behaviour as Data

```
assume(1 <= n <= 1000);
sum = 0, i = 1;
while(i<=n) {
    sum = sum + i;
    i = i + 1;
}
assert(2*sum == n*(n+1));
```

Safe Inductive invariant:

$$2 * \mathit{sum} = i * (i - 1) \wedge i \leq n + 1$$

Behaviour as Data

```
assume(1 <= n <= 1000);
sum = 0, i = 1;
if(i<=n) {                                <0 , 1>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <1,  2>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <3,  3>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <6,  4>
    sum = sum + i;
    i = i + 1;
}
```

Behaviour as Data

```
assume(1 <= n <= 1000);
sum = 0, i = 1;
if(i<=n) {                                <0, 1>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <1, 2>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <3, 3>
    sum = sum + i;
    i = i + 1;
}
if(i<=n) {                                <6, 4>
    sum = sum + i;
    i = i + 1;
}
```

If an invariant is a conjunction of k polynomial equations each of degree d and nullity of A is k , where A is a data matrix, then any basis for nullspace of A forms an invariant.

Sharma et al, ESOP, 2013

Behaviour as Data

```
assume(1 <= n <= 1000);  
sum = 0, i = 1;  
if(i<=n) {                                <0, 1>  
    sum = sum + i;  
    i = i + 1;  
}  
if(i<=n) {                                <1, 2>  
    sum = sum + i;  
    i = i + 1;  
}  
if(i<=n) {                                <3, 3>  
    sum = sum + i;  
    i = i + 1;  
}  
if(i<=n) {                                <6, 4>  
    sum = sum + i;  
    i = i + 1;  
}
```

Inductive invariant:

$$a * sum^2 + b * i^2 + c * sum * i + d * sum + e * i + f = 0$$

Algebraic Invariants

1	sum	i	sum^2	$sum * i$	i^2
1	0	1	0	0	1
1	1	2	1	2	4
1	3	3	9	9	9
1	6	4	36	24	16
1	10	5	100	50	25

Algebraic Invariants

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 2 & 1 & 2 & 4 \\ 1 & 3 & 3 & 9 & 9 & 9 \\ 1 & 6 & 4 & 36 & 24 & 16 \\ 1 & 10 & 5 & 100 & 50 & 25 \end{bmatrix} * \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} = 0$$

Algebraic Invariants

$$\text{basis}(\text{Nullspace}(M)) = \begin{bmatrix} 0 \\ -2 \\ -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$0 * 1 - 2 * \text{sum} - 1 * i + 0 * \text{sum}^2 + 0 * \text{sum} * i + 1 * i^2$$

$$2 * \text{sum} = i * (i - 1)$$

Conditional Invariants

```
int LRG = nondet();
assume(LRG > 0);

int x = 0, y = LRG;

while(x < 2*LRG) {
  if (x < LRG) {
    y = y;
  } else {
    y = y + 1;
  }
  x = x + 1;
}
assert(y == 2*LRG);
```

Conditional Invariants

```
int LRG = nondet();  
assume(LRG > 0);
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```
int x = 0, y = LRG;
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```
while(x < 2*LRG) {  
  if (x < LRG) {  
    y = y;  
  } else {  
    y = y + 1;  
  }  
  x = x + 1;  
}  
assert(y == 2*LRG);
```

Disjunctive:

$$((x \geq \text{LRG}) \vee$$
$$(y = x) \wedge$$
$$(x \leq 2 * \text{LRG}))$$

Conditional Invariants

```
int LRG = nondet();
assume(LRG > 0);

int x = 0, y = LRG;

while(x < 2*LRG) {
  if (x < LRG) {
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}
assert(y == 2*LRG);
```

Disjunctive:

$$((x \geq \text{LRG}) \vee (y = x) \wedge (x \leq 2 * \text{LRG}))$$

Conditional Invariants:

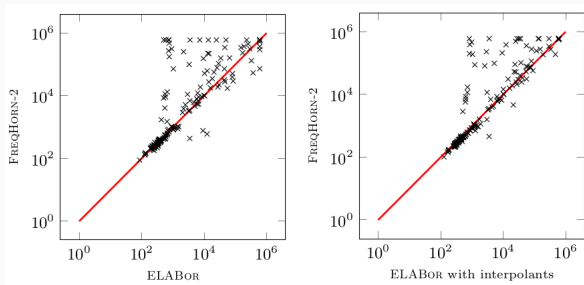
$$(((x < \text{LRG}) \Rightarrow (y = \text{LRG})) \wedge ((x \geq \text{LRG}) \Rightarrow (y = x))) \wedge (x \leq 2 * \text{LRG})$$

CTIs: $s_k \models \text{Inv}$ and $(s_k, s'_{k+1}) \models \text{Tr}$,
but $s'_{k+1} \not\models \text{Inv}'$

Results

ELABOR solved 16/24 new programs when compared to FREQHORN-2

2x speedup and 100s time difference for 31 programs



Future Directions

Usage in solving nested loops (*In Review*)

Neural nets to refine sampling

Deciding between behaviour or appearance

Conclusion

Appearance guided synthesis

Behaviours to obtain candidates

Conditional invariants for disjunctions

References



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Algorithm 5 ELABOR: Learning from Behaviours and CTIs

Input: $Init, Tr, Bad$ and V
Output: $lemmas$

- 1: $behaviours \leftarrow EXECUTE(Init, Tr, Bad)$
- 2: $candidates \leftarrow GETALGEBRAICCANDIDATES(behaviours)$
- 3: $\mathcal{P} \leftarrow COMPUTEDISTRIBUTION(Init, Tr, Bad)$
- 4: $G \leftarrow CONSTRUCTGRAMMAR(\mathcal{P})$
- 5: $\mathcal{P}_a \leftarrow COMPUTEDISTRIBUTION(Tr_{conds})$
- 6: $G_a \leftarrow CONSTRUCTGRAMMAR(\mathcal{P}_a)$
- 7: $L \leftarrow \emptyset$ \triangleright the set of lemmas
- 8: $disjunct \leftarrow false$
- 9: **while** $\bigwedge_{l \in L} l(V) \wedge Bad(V)$ is SAT **do**
- 10: **if** $\neg disjunct$ **then** $disjunct \leftarrow CHECKFORIMPL(CTIs)$
- 11: **if** $disjunct$ **then** $antecedent \leftarrow NEWCANDIDATE(G_a)$
- 12: **while** $|candidates| < BatchSize$ **do** \triangleright for a pre-decided $BatchSize$
- 13: $cand \leftarrow NEWCANDIDATE(G)$
- 14: **if** $init \leftarrow Init(V) \wedge \neg cand(V)$ is UNSAT **then**
- 15: **if** $disjunct$ **then** $candidates \leftarrow candidates \cup \{antecedent \Rightarrow cand\}$
- 16: **else** $candidates \leftarrow candidates \cup \{cand\}$
- 17: **else** $ADJUST(cand, G, \mathcal{P})$
- 18: **for** $cand \in candidates$ **do**
- 19: **if** $consec \leftarrow \bigwedge_{c \in candidates} c(V) \wedge \bigwedge_{l \in L} l(V) \wedge Tr(V, V') \wedge \neg cand(V')$ is SAT **then**
- 20: $candidates \leftarrow candidates \setminus \{cand\}$
- 21: $ADJUST(cand, G, \mathcal{P})$
- 22: $CTIs \leftarrow CTIs \cup \{GETMODEL(V)\} \cup \{GETMODEL(V')\}$
- 23: $candidates.reset$ \triangleright start the loop afresh
- 24: **if** $disjunct \wedge |candidates| > 0$ **then** $ADJUST(antecedent, G_a, \mathcal{P}_a)$
- 25: **for** $cand \in candidates$ **do** $L \leftarrow L \cup \{cand\}$
- 26: **return** L

Conditional Invariants

$$\begin{aligned} \text{Polynomial relation: } x'_i \in V', \\ f(x'_i) = \\ c_1 * m_1 + c_2 * m_2 + \dots + c_n * m_n \end{aligned}$$

Conditional Invariants

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$$\begin{aligned} \text{CTIs: } s_k \models \text{Inv} \text{ and } (s_k, s'_{k+1}) \models \text{Tr}, \\ \text{but } s'_{k+1} \not\models \text{Inv}' \end{aligned}$$

Conditional Invariants

Polynomial relation: $x'_i \in \mathcal{V}$,

$$f(x'_i) =$$

$$c_1 * m_1 + c_2 * m_2 + \dots + c_n * m_n$$

CTIs: $s_k \models \text{Inv}$ and $(s_k, s'_{k+1}) \models \text{Tr}$,
but $s'_{k+1} \not\models \text{Inv}'$

M matrix of monomials from s_k

$$\vec{f}_{x'_i}^T = (x'_{i_1} \quad \dots \quad x'_{i_l}) \text{ from } s'_{k+1}$$

Conditional Invariants

Polynomial relation: $x'_i \in \mathcal{V}$,

$$f(x'_i) =$$

$$c_1 * m_1 + c_2 * m_2 + \dots + c_n * m_n$$

CTIs: $s_k \models \text{Inv}$ and $(s_k, s'_{k+1}) \models \text{Tr}$,
but $s'_{k+1} \not\models \text{Inv}'$

M matrix of monomials from s_k

$$\vec{f}_{x'_i}^T = (x'_{i_1} \quad \dots \quad x'_{i_l}) \text{ from } s'_{k+1}$$

$\text{rank}(\mathbf{M}) \neq \text{rank}((\mathbf{M} | \vec{f}_{x'_i}))$ no
solution over $c_1 \dots c_n$

Conditional Invariants

```
int LRG = nondet();
assume(LRG > 0);

int x = 0, y = LRG;

while(x < 2*LRG) {
  if (x < LRG) {
    y = y;
  } else {
    y = y + 1;
  }
  x = x + 1;
}
assert(y == 2*LRG);
```

$$y = LRG$$

$$s_k(LRG) = 100, s_k(x) = 100, \\ s_k(y) = 100$$

$$s'_{k+1}(LRG') = 100,$$

$$s_{k+1}(x') = 101,$$

$$s_{k+1}(y') = 101$$

Conditional Invariants

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  x = x + 1;
}
assert(y == 2*LRG);
```

$y = LRG$

$s_k(LRG) = 100, s_k(x) = 100,$
 $s_k(y) = 100$

$s'_{k+1}(LRG') = 100,$
 $s_{k+1}(x') = 101,$
 $s_{k+1}(y') = 101$

$y = x$

$s_k(LRG) = 100, s_k(x) = 10,$
 $s_k(y) = 100$

$s'_{k+1}(LRG') = 100,$
 $s_{k+1}(x') = 11,$
 $s_{k+1}(y') = 100$

Conditional Invariants

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int LRG = nondet();
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  if (x < LRG) {
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  } else {
    y = y + 1;
  }
  x = x + 1;
}
assert(y == 2*LRG);
```

$$\text{Rank} \begin{bmatrix} \text{const} & \text{LRG} & x & y \\ 1 & 100 & 100 & 100 \\ 1 & 100 & 10 & 100 \\ \dots & & & \end{bmatrix}$$

\neq

$$\text{Rank} \begin{bmatrix} \text{const} & \text{LRG} & x & y & y' \\ 1 & 100 & 100 & 100 & 101 \\ 1 & 100 & 10 & 100 & 100 \\ \dots & & & & \end{bmatrix}$$

The cardinality of \mathbf{B} is called *dimension* of \mathbf{V} . For a matrix \mathbf{A} , the dimension of the vector space generated by its columns is called its *rank*. The *nullspace* of a matrix \mathbf{A} is a set of all vectors \mathbf{v} such that $\mathbf{A}\mathbf{v} = \mathbf{0}$. The dimension of a matrix's nullspace is also called its *nullity*.