Counterexample-Guided Quantifier Instantiation for Synthesis in SMT

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Outline

- ► The Problem
- Restrictions
- Solutions

The (Synthesis) Problem

Synthesize a function that meets a given specifications.

- Example Synthesize f such that:
 - $f(x_1, x_2) \ge x_1 \land$
 - $f(x_1, x_2) \geq x_2 \wedge$
 - $f(x_1, x_2) \approx x_1 \lor f(x_1, x_2) \approx x_2$
- Applicable in synthesis of functional programs, program sketching, synthesis of reactive systems, etc.

If P is a formula that encodes the specification,

$$egin{aligned} & P[f, x_1, x_2] = f\left(x_1, x_2
ight) \geq x_1 \, \wedge \, f\left(x_1, x_2
ight) \geq x_2 \, \wedge \ & \left(f\left(x_1, x_2
ight) pprox x_1 ee f\left(x_1, x_2
ight) pprox x_2
ight) \end{aligned}$$

then we must have

 $\forall x_1x_2. P[f, x_1, x_2]$

And the question that we are asking is

 $\exists f. \forall x_1 x_2. P[f, x_1, x_2]$

► Or, more generally,

$$\underbrace{\exists f.}_{\text{Exists a function s.t.}} \underbrace{\forall x_1, x_2, \dots x_n. P(f, x_1, x_2, \dots x_n)}_{\text{for all } \bar{x}, P(f, \bar{x}) \text{ is true}}$$

- ► An SMT solver may treat f as an uninterpreted function, but the real challenge here is the universal quantification over x̄.
- The solver must construct (a finite representation of) an interpretation for f which is *true* for all \bar{x} .

- In contrast, there are effective techniques to show unsatisfiability of universally quantified formulas.
- SMT solvers use instantiation-based methods generate ground instances until a refutation is found.
- Can we transform our problem into one of checking unsatisfiability?

If satisfiability $(F) \Rightarrow$ validity (F),

 $(F \text{ is sat}) \Leftrightarrow (\neg F \text{ is not valid}) \Leftrightarrow (\neg F \text{ is unsatisfiable})$

Restriction

- 1. Satisfiability \Rightarrow Validity
 - In other words, we will only consider theories that are <u>satisfaction complete</u> wrt the formulas we are interested in.
 - Most theories used in SMT (e.g. various theories of integers, reals, strings, algebraic datatypes, bit-vectors, etc.) are satisfaction complete wrt the class of closed first-order formulas.



- Another challenge: Negation introduces second-order universal quantification (over function f).
- ▶ What if we restrict ourselves to the class of synthesis problems $\exists f . \forall \bar{x} . P[f, \bar{x}]$, where every occurrence of f in P is of the form $f(\bar{x})$.
- ▶ In that case, we can transform the synthesis problem to: $\forall \bar{x} . \exists y . Q[\bar{x}, y]$.

Restrictions

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- 2. P consists of single-invocation properties

 $f(x_1, x_2) \ge x_1 \wedge f(x_1, x_2) \ge x_2 \wedge (f(x_1, x_2) \approx x_1 \vee f(x_1, x_2) \approx x_2)$

 $c(x_1,x_2)\approx c(x_2,x_1)$

Recall

Synthesis conjecture:

$$\exists f. \forall x_1...x_n. P[f, x_1, ..., x_n]$$

- avoid second-order quantification, and
- solve an unsatisfiability (universal quantification) problem instead of a satisfiability one.

So far..



Our first example

 $\exists f. \ \forall x_1x_2.(f(x_1, x_2) \geq x_1 \land f(x_1, x_2) \geq x_2 \land (f(x_1, x_2) \approx x_1 \lor f(x_1, x_2) \approx x_2)) \text{ sat}$

(single-invocation property)

$$orall x_1 x_2$$
. $\exists g$. $(g \geq x_1 \land g \geq x_2 \land (g pprox x_1 \lor g pprox x_2))$ sat

hegate (satisfaction-complete theory)

$$\exists x_1 x_2. \ orall g. \ (g < x_1 \lor g < x_2 \lor (g
ot \approx x_1 \land g
ot pprox x_2)) \ {\sf unsat}$$

Skolemize, for fresh a, b

 $\forall g. (g < a \lor g < b \lor (g \not\approx a \land g \not\approx b))$ unsat

Solving Max Example



Ground solver

Solving Max Example





Solving Max Example





 $\neg P(t_1, \mathbf{k}), ..., \neg P(t_n, \mathbf{k}) \mid = false$



Found
$$\neg P(t_1, \mathbf{k}), \dots, \neg P(t_n, \mathbf{k}) \mid = false$$

Claim the following is a solution for f:

$$\lambda \mathbf{x}$$
. ite(P(t₁, \mathbf{k}), t₁,
ite(P(t₂, \mathbf{k}), t₂,
...
ite(P(t_{n-1}, \mathbf{k}), t_{n-1},
t_n)...) [\mathbf{x}/\mathbf{k}]

Found
$$\neg P(t_1, \mathbf{k}), \dots, \neg P(t_n, \mathbf{k}) | = false$$

Claim the following is a solution for f:

$$\lambda \mathbf{x}$$
. ite(P(t₁, \mathbf{k}), t₁,
ite(P(t₂, \mathbf{k}), t₂,
...
ite(P(t_{n-1}, \mathbf{k}), t_{n-1},
t_n)...) [\mathbf{x}/\mathbf{k}]

- If P holds for t_1 , return t_1

Found
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Claim the following is a solution for f:

$$\lambda \mathbf{x}$$
. ite(P(t₁, \mathbf{k}), t₁,
ite(P(t₂, \mathbf{k}), t₂,
...
ite(P(t_{n-1}, \mathbf{k}), t_{n-1},
t_n)...) [\mathbf{x}/\mathbf{k}]

 \rightarrow If P holds for t_2 , return t_2

Found
$$\neg P(t_1, \mathbf{k}), \dots, \neg P(t_n, \mathbf{k}) | = false$$

$$\begin{array}{c} \text{Claim the following is a solution for f:} \\ \lambda \textbf{x. ite(P(t_1, \textbf{k}), t_1, \\ ite(P(t_2, \textbf{k}), t_2, \\ ... \\ ... \\ ite(P(t_{n-1}, \textbf{k}), t_{n-1}, \\ t_n) ...) [\textbf{x}/\textbf{k}] \end{array} \right] \rightarrow \text{If P holds for } t_{n-1}, \text{ return } t_{n-1} \\ \end{array}$$

Found
$$\neg P(t_1, \mathbf{k}), \dots, \neg P(t_n, \mathbf{k}) | = false$$

Claim the following is a solution for f:

$$\lambda \mathbf{x}$$
. ite (P(t₁, \mathbf{k}), t₁,
ite (P(t₂, \mathbf{k}), t₂,
...
ite (P(t_{n-1}, \mathbf{k}), t_{n-1},
 t_n)...) [\mathbf{x}/\mathbf{k}] \rightarrow Why does P(t_n, \mathbf{k}) hold?

Solution for Max Example

Given $\exists f. \forall xy. (f(x, y) \ge x \land f(x, y) \ge y \land (f(x, y) = x \lor f(x, y) = y))$

Found
$$\neg (a \ge a \land a \ge b \land (a = a \lor a = b)), = false$$

Claim the following is a solution for f: λxy. ite(a≥a ∧ a≥b ∧ (a=a ∨ a=b), a, b)...) [x/a] [y/b]

Solution for Max Example

Given $\exists f. \forall xy. (f(x, y) \ge x \land f(x, y) \ge y \land (f(x, y) = x \lor f(x, y) = y))$

Found
$$\neg (a \ge a \land a \ge b \land (a = a \lor a = b)), = false$$

Claim the following is a solution for f: λxy . ite ($x \ge x \land x \ge y \land (x = x \lor x = y)$, x, y)...)

Solution for Max Example

Given $\exists f. \forall xy. (f(x, y) \ge x \land f(x, y) \ge y \land (f(x, y) = x \lor f(x, y) = y))$

Found
$$\neg (a \ge a \land a \ge b \land (a = a \lor a = b)), = false$$

Claim the following is a solution for f: λxy . ite ($x \ge_Y$, x , y)

Lifting the single-invocation property restriction

- Can we still refute negated synthesis conjectures?
- ► Yes, under syntactic restrictions.

Example: Syntax-Guided Synthesis

> Syntactic restriction for the solution space, expressed by these algebraic datatypes:

$$S := t_1 | t_2 | zero | one | plus(S, S) | minus(S, S) | if (C, S, S) C := leq(S, S) | eq(S, S) | and(C, C) | not(C)$$

Example: Syntax-Guided Synthesis

Syntactic restriction for the solution space, expressed by these algebraic datatypes:

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- And an interpretation of these datatypes in terms of the original theory.
 - 1. $ev^{S \times Int \times Int \rightarrow Int}$: embedding S in Int.
 - 2. $ev^{C \times Int \times Int \rightarrow Bool}$: embedding *C* in Bool.

The evaluation operators



Another example

$$P[c, x_1, x_2] = c(x_1, x_2) \approx c(x_2, x_1)$$

can be restated as follows, where g is a variable of type S:

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

Now, instead of finding a witness for ∃c. ∀x₁x₂.P[c, x₁, x₂] we will determine the unsatisfiability of ∃x₁x₂. ∀g.¬P_{ev}[g, x₁, x₂].

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$



$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

Model	Added Formula
$[g ightarrow t_1]$	$ev(t_1,a_1,b_1) \not\approx ev(t_1,b_1,a_1)$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

Model	Added Formula
$[g ightarrow t_1]$	$ev(t_1,a_1,b_1) ot\approx ev(t_1,b_1,a_1)$
$[a_1 ightarrow 1, b_1 ightarrow 0]$	$G \Rightarrow \mathit{ev}(g,1,0) pprox \mathit{ev}(g,0,1)$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

$egin{aligned} & [g ightarrow t_1] & ev(t_1, a_1, b_1) otin ev(t_1, b_1, a_1) \ & [a_1 ightarrow 1, b_1 ightarrow 0] & G \Rightarrow ev(g, 1, 0) pprox ev(g, 0, 1) \ & [g ightarrow zero] & ev(zero, a_2, b_2) otin ev(zero, b_2, a_2) \end{aligned}$	Model	Added Formula
$egin{aligned} & [a_1 ightarrow 1, b_1 ightarrow 0] & G \Rightarrow \mathit{ev}(g, 1, 0) pprox \mathit{ev}(g, 0, 1) \ & [g ightarrow \mathit{zero}] & \mathit{ev}(\mathit{zero}, a_2, b_2) ot pprox \mathit{ev}(\mathit{zero}, b_2, a_2) \end{aligned}$	$[g ightarrow t_1]$	$ev(t_1,a_1,b_1) ot\approx ev(t_1,b_1,a_1)$
$[g ightarrow \textit{zero}] \qquad \textit{ev}(\textit{zero}, \textit{a}_2, \textit{b}_2) ot\approx \textit{ev}(\textit{zero}, \textit{b}_2, \textit{a}_2)$	$[a_1 ightarrow 1, b_1 ightarrow 0]$	$G \Rightarrow \mathit{ev}(g,1,0) pprox \mathit{ev}(g,0,1)$
	$[g ightarrow {\it zero}]$	$ev(zero, a_2, b_2) \not\approx ev(zero, b_2, a_2)$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

Model	Added Formula
$[g ightarrow t_1]$	$\mathit{ev}(t_1, a_1, b_1) ot\approx \mathit{ev}(t_1, b_1, a_1)$
$[a_1 ightarrow 1, b_1 ightarrow 0]$	$G \Rightarrow \mathit{ev}(g,1,0) pprox \mathit{ev}(g,0,1)$
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none	

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \approx ev(g, x_2, x_1)$$

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$[g ightarrow t_1]$	$ev(t_1,a_1,b_1) ot\approx ev(t_1,b_1,a_1)$
$[a_1 ightarrow 1, b_1 ightarrow 0]$	${\it G} \Rightarrow {\it ev}(g,1,0) pprox {\it ev}(g,0,1)$
[g ightarrow zero]	$ev(zero, a_2, b_2) ot\approx ev(zero, b_2, a_2)$
none	
So	lution: $c(x_1, x_2) = 0$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \not\approx ev(g, x_2, x_1)$$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \not\approx ev(g, x_2, x_1)$$



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Model	Added Formula
$[g ightarrow t_1]$	$\mathit{ev}(\mathit{t}_1, \mathit{a}_1, \mathit{b}_1) \approx \mathit{ev}(\mathit{t}_1, \mathit{b}_1, \mathit{a}_1)$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \not\approx ev(g, x_2, x_1)$$

M	odel	Added Formula
[g	$t ightarrow t_1]$	$\mathit{ev}(t_1, \mathit{a}_1, \mathit{b}_1) \approx \mathit{ev}(t_1, \mathit{b}_1, \mathit{a}_1)$
$[a_1 \rightarrow$	$0, b_1 ightarrow 0]$	$G \Rightarrow \mathit{ev}(g,0,0) ot\approx \mathit{ev}(g,0,0)$

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \not\approx ev(g, x_2, x_1)$$

$[g \rightarrow t_1] \qquad ev(t_1, a_1, b_1) \approx ev(t_1, b_1, a_1)$	Model	Added Formula
	$[g ightarrow t_1]$	$ev(t_1,a_1,b_1)pprox ev(t_1,b_1,a_1)$
$[a_1 ightarrow 0, b_1 ightarrow 0] G \Rightarrow \mathit{ev}(g,0,0) ot\approx \mathit{ev}(g,0,0)$	$_1 ightarrow 0, b_1 ightarrow 0]$	$G \Rightarrow \textit{ev}(g,0,0) ot\approx \textit{ev}(g,0,0)$
none	none	

$$P_{ev}[g, x_1, x_2] = ev(g, x_1, x_2) \not\approx ev(g, x_2, x_1)$$

Model	Added Formula
$[g ightarrow t_1]$	$ev(t_1, a_1, b_1) pprox ev(t_1, b_1, a_1)$
$[a_1 ightarrow 0, b_1 ightarrow 0]$	$G \Rightarrow \mathit{ev}(g,0,0) ot\approx \mathit{ev}(g,0,0)$
none	
	No Solution

The procedure has following properties:

- Solution Soundness: Every term that it returns can be mapped to a solution of the original synthesis conjecture ∃f. ∀x̄. P[f, x̄].
- Refutation Soundness: If it does not find a solution (up to a given length), the original conjecture has no solution under the syntactic restrictions up to that length.
- Solution Completeness: If the original synthesis conjecture has a solution under these restrictions, the procedure will find one.

To conclude

- Refutation based approach for syntax-guided synthesis.
- ▶ Implemented in CVC4; winner in General and LIA tracks at SyGuS-Comp 2014.
- Single-invocation appears to be restrictive but not quite so in practice; 176 benchmarks out of 243 at SyGuS-Comp 2014 were single-invocation.

Thank you.

Questions?